

Software Version 2.22 or above

Internal Database Version 2.01 © Navionics Corporation

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INTRODUCTION Foreword

GARMIN<sup>TM</sup>, GPSMAP<sup>TM</sup>, G-chart<sup>TM</sup>, AutoLocate<sup>TM</sup>, TracBack<sup>TM</sup> and PhaseTrac12<sup>TM</sup> are trademarks of GARMIN International and may only be used with permission. All rights are reserved. INTRODUCTION Cautions

#### CAUTION!

The GARMIN GPSMAP 130 has no user-serviceable parts. Should you ever encounter a problem with your unit, please take it to an authorized GARMIN dealer for repairs.

The GPSMAP 130 is sealed and filled with dry nitrogen. Any attempt to open the case to change or modify the unit in any way will void your warranty and may result in permanent damage to the equipment.

# CAUTION

The GPS system is operated by the United States government, which is solely responsible for its accuracy and maintenance. The system is subject to changes which could affect the accuracy and performance of all GPS equipment. Although the GARMIN GPSMAP 130 is a precision electronic NAVigation AID (NAVAID), any NAVAID can be misused or misinterpreted and, therefore, become unsafe.

Use the GPSMAP 130 at your own risk. To reduce the risk of unsafe operation, carefully review and understand all aspects of this Owner's Manual—and thoroughly practice operation using the simulator mode prior to actual use. When in actual use, carefully compare indications from the GPSMAP 130 to all available navigation sources, including the information from other NAVAIDs, visual sightings, charts, etc. For safety, always resolve any discrepancies before continuing navigation.

NOTE: This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference, the user is encouraged to try to correct the interference by relocating the equipment or connecting the equipment to a different circuit. Consult an authorized dealer or other qualified technician for additional help if these remedies do not correct the problem.

This device complies with Part 15 of the FCC limits for class B digital devices. Operation is subject to the following conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

The GPSMAP 130 contains no user-serviceable parts. Repairs should only be made by an authorized service center. Unauthorized repairs or modifications could void your warranty and your authority to operate this device under Part 15 regulations.

Designed for detailed electronic charting and simple operation, the GARMIN GPSMAP 130 is a powerful navigation device that can help guide you in waterways around the world:

# **Precision Performance**

- High-contrast LCD screen
- $\bullet$  PhaseTrac12  $^{\rm TM}$  receiver tracks and uses up to 12 satellites simultaneously for fast, accurate positioning
- Differential-Ready— just add the optional GBR 21 beacon receiver for better than 10-meter accuracy
- Waterproof, dry nitrogen-filled case for use in exposed locations

# Advanced Navigating and Plotting

- 250 alphanumeric waypoints with selectable icons and comments
- Built-in worldwide database usable from 4096 to 64 nm scales
- 20 reversible routes with up to 30 waypoints each
- $\bullet$  G-chart  ${}^{\scriptscriptstyle{\rm TM}}$  electronic charting with inland and offshore coverage
- On-screen point-to-point distance and bearing calculations
- $\bullet$  TracBack^{\ensuremath{^{\rm TM}}} route feature which allows you to quickly retrace your track log to a starting position
- Built-in simulator mode





# LIMITED WARRANTY

GARMIN warrants this product to be free from defects in materials and workmanship for one year from the date of purchase. GARMIN International, Inc. will at its sole option, repair or replace any components which fail in normal use. Such repairs or replacement will be made at no charge to the customer for parts or labor. The customer is, however, responsible for any transportation costs. This warranty does not cover failures due to abuse, misuse, accident or unauthorized alteration or repairs. GARMIN International, Inc. assumes no responsibility for special, incidental, punitive or consequential damages, or loss of use.

The warranties and remedies contained herein are exclusive, and in lieu of all other warranties expressed or implied, including any liability arising under warranty of merchantability or fitness for a particular purpose, statutory or otherwise. This warranty gives you specific legal rights, which may vary from state to state.

To obtain warranty service, call the GARMIN Customer Service department for a returned merchandise tracking number. The unit should be securely packaged with the tracking number clearly marked on the outside of the package, and sent freight prepaid and insured to a GARMIN warranty service station. A copy of the original sales receipt is required as the proof of purchase for warranty repairs. GARMIN retains the exclusive right to repair or replace the unit or software at its sole discretion.

# Preface

Congratulations on choosing one of the most advanced marine navigation systems available! The GARMIN GPSMAP 130 combines the proven performance of GARMIN GPS with powerful G-Chart electronic charting for detailed cartography and plotting wherever you cruise.

To get the most out of your new navigation system, take the time to go through this operator's manual and learn the operating procedures for your unit. This manual is broken down into two sections for your convenience.

**Part One** introduces you to the GPSMAP 130 and provides a getting started section so that you may become more familiar with the unit. This part will provide you with a basic working knowledge necessary to use the unit to it's fullest potential.

**Part Two** is divided into sections that provide detailed references to the advanced features and operations of the GPSMAP 130. This allows you to concentrate on a specific topic quickly, without reading through entire portions of text that you may not need. This section can be used to look up further information about the GPSMAP 130.

# INTRODUCTION Preface

#### WARNING!

The electronic chart is an aid to navigation and is designed to facilitate the use of authorized government charts, not replace them. Only official government charts and notices to mariners contain all information needed for the safety of navigation-and, as always, the user is responsible for their prudent use.



Before installing and getting started with your unit, please check to see that your package includes the following items. If any parts are missing, please see your GARMIN dealer immediately.

Standard Package:

- GPSMAP 130 Unit
- External Antenna and 30' cable
- Power/Data Cable
- Mounting Bracket
- Owner's Manual
- Quick Reference Card

Optional Accessories:

- G-chart Electronic Chart Cartridges
- PC Kit

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INTRODUCTION Keypad Usage

The GPSMAP 130's advanced keypad system is designed to allow for fast, convenient selection of navigation options and data entry.

The Getting Started Tour will introduce you to most of the keypad and provide a 'hands-on' lesson in using the GPSMAP 130. We strongly encourage you to take the Getting Started tour before using your unit for actual navigation.

The GPSMAP 130 Quick Reference Card contains helpful tips on using the unit and performing various navigation tasks. It's a good idea to keep the Quick Reference Card nearby whenever you're navigating with your new GPS chartplotter.

	Turns the unit on and off and controls 3-level screen backlighting.
PAGE	Scrolls the main pages in sequence and returns display from a submenu page to a main page.
MARK	Captures your present position and displays the mark position window.
GOTO	Displays the GOTO waypoint window, allowing you to select the destination waypoint. Press GOTO twice to select a destination waypoint graphically from the map.
MENU	Displays context-sensitive options window. Press MENU twice to display main menu page.
EDIT ENTER	Activates highlighted fields and confirms menu options and data entry.
QUIT	Returns display to a previous page or restores a data field's previous value.
ZOOM	Adjusts the map and highway scales up and down.
	Controls the movement of the cursor and is used to select options and positions, and to enter data.
МОВ	Marks your present GPS position and instantly sets a return course while providing steering guidance.

# Initializing the Receiver

The first time you power up your new GPSMAP 130 is an important step in getting the best possible GPS performance. The receiver must be given an opportunity to collect satellite data and establish its present position. To ensure proper initialization, the GPSMAP 130 is shipped from the factory in AutoLocate<sup>™</sup> mode, which will allow the receiver to 'find itself' anywhere in the world. To speed up the initialization process, we recommend using the graphic initialization process described below, which will usually provide a position fix in about a minute.

Before you initialize, make sure the GPSMAP unit and antenna have been correctly installed on your vessel according to the instructions in Appendix A.

#### To turn the GPSMAP 130 on:

#### 1. Press and hold the 📧 key until the power tone sounds.

The welcome page will appear while the unit conducts a self test. Once the internal test is complete, the mariner's warning will appear, asking you to read and acknowledge important information regarding the proper use of electronic charts.

#### To acknowledge the mariner's warning:

1. Press the ENTER key.

A message alert and prompt will also appear to ask you to select an initialization method.

#### To view a system message:

1. Press the PAGE key.

2. Press the PAGE key again to return to the previous page.



- **A.** The welcome page will be displayed while the unit performs a self-test.
- **B.** Confirm the Mariner's Warning before starting navigation. Remember that the electronic chart is designed as a supplement to local government charts, not as a replacement.



- **A.** Use the arrow keypad to move the cursor to a location close to your present position.
- **B.** Hollow signal strength bars will appear on the status page while the receiver collects satellite data.

The select initialization window will appear, with the 'select from map' option highlighted.

1. Press 🛲 to initialize the receiver from the built-in worldwide map.

The map page will appear, prompting you to select your approximate present position with the map cursor.

1. Use the respectively to move the map cursor to a location close to your present position. If you have difficulty identifying your exact position, use the bottom arrow of the respectively to zoom in to a lower map scale.

2. Press entry to confirm your selection.

The GPSMAP 130 will now begin searching for the appropriate satellites for your present position and should acquire a fix within a minute or so. While the receiver searches for satellites, a flashing satellite icon will appear at the left-hand side of the status bar. A signal strength bar will also appear for each satellite in view, with the appropriate satellite number under each bar. The progress of satellite acquisition is shown in three stages:

- No signal strength bars— the receiver is looking for the satellites indicated.
- Hollow signal strength bars— the receiver has found the indicated satellite(s) and is collecting data.
- **Solid signal strength bars** the receiver has collected the necessary data and the satellite(s) is ready for use.

Once the receiver has collected information from at least three satellites, the flashing satellite icon on the status bar will glow steadily, and the GPSMAP 130 is ready for use.

# **GPSMAP 130 Getting Started Tour**

The GARMIN GPSMAP 130 is a powerful electronic charting/navigating system that provides detailed chart coverage and convenient control of many advanced features right from the map display. This tour is designed to take you through the basic pages and functions of the system using the simulator mode. Once you're familiar with the main pages and functions of the unit, refer to the reference section for instructions on performing specific tasks and functions.

The Getting Started tour assumes that the receiver has been properly installed and initialized, and you have not changed any of the default unit settings. If you have changed any settings (position formats, units of measure, etc.), the descriptions and pictures in the tour may not match your configuration.

#### To turn the GPSMAP 130 on:

- 1. Press and hold the set will appear while the unit conducts a self test.
- 2. Once the self test is complete, press the ERE key to acknowledge the mariner's warning.

The satellite status page will appear, and the receiver will begin to acquire satellites. From the status page, you may also quickly adjust the screen contrast and backlighting.

#### To adjust the screen contrast:

- 1. To increase the screen contrast, press the right arrow of the 🔘 keypad.
- 2. To decrease the screen contrast, press the left arrow of the 🜑 keypad.

3. Press the ERE key to finish.

The GPSMAP 130's three-level screen backlighting is controlled with **s** key, and may be adjusted at any time from any page.

#### To turn on and adjust the backlighting:

1. Press the esired level (off, 1, 2, or 3).



- **A.** The screen contrast may be adjusted from the status page by pressing the ARROW KEYPAD. Press EDIT/ENTER to confirm changes.
- **B.** Whenever the screen backlighting is on, a bulb icon will appear in the status bar at the bottom of every GPSMAP 130 page.



- **A.** To start the simulator, confirm the simulator warning. Simulator mode should never be used for actual navigation.
- **B.** Whenever the GPSMAP 130 is in simulator mode, a 'Setup Simulator?' and an 'Exit Simulator?' option will appear on the options page.



The GPSMAP 130's **status page** provides a visual reference of satellite acquisition and receiver status, with a signal strength bar graph and a satellite sky view in the center of the page. Each page of the GPSMAP 130's system also features an options page, which gives you access to other functions and features that relate to the specific page you are viewing. To get a feel for how the options pages work, lets put the GPSMAP 130 into simulator mode.

#### To place the GPSMAP 130 in simulator mode:

- 1. From the status page, press the wave key. The options page will appear, displaying a menu of options and functions for the status page.
- 2. Use the UP or DOWN arrow of the () keypad to highlight the 'Start Simulator?' option and press [].
- 3. Press the ENE key to confirm the simulator warning.

Once the simulator has been started, the status field at the top of the page will display a 'Simulating Navigation' status, and you're ready to continue the rest of the tour. Keep in mind that the GPSMAP 130 does not track satellites in simulator mode, and should never be used for actual navigation. All the waypoint and route planning done in simulator mode will still be retained in memory for future use.



The satellite status page is one of four main pages used in the GPSMAP 130's system. All four pages are linked together in a simple chain, which allows you to scroll through the pages in either direction using the rest and rest keys. To continue the tour, let's move on to the next page, the position page.

#### To scroll to the next page in sequence:

#### 1. Press the PAGE key.

The GPSMAP 130's **position page** shows where you are, what direction you're heading and how fast you're going. The compass at the top of the page indicates the direction you're moving. The four user-selectable data fields below the compass tape show your current course and speed over ground, along with a resettable trip odometer and altitude display. Your current latitude and longitude, along with a 12/24-hour clock, appear at the bottom of the page.

Now that you've seen how the status and position pages can be used to monitor satellite acquisition and your present position, let's take a minute to learn how to mark and store our present position as a waypoint. (Since we're in simulator mode, the present position displayed will be the last position calculated by the receiver, which should be the spot where you've initialized the unit.) This will also give you an opportunity to see how the GPSMAP 130's reveal and rev





- **A.** The mark position page will automatically assign a default three-digit name for each waypoint, which can be changed at any time to an alphanumeric name containing up to six-characters.
- **B.** A complete set of waypoint symbols allows you to mark inland and offshore waypoints with a custom icon for fast waypoint recognition.

#### To mark your present position:

- 1. Press the ware key. The mark position page will appear, with a default three-digit waypoint name and symbol.
- 2. Use the  $\bigcirc$  keypad to highlight the waypoint name field (001) and press  $\blacksquare$
- 3. Press the LEFT ARROW of the 🗼 keypad to clear the name field.



- 4. Use the keypad to enter the name 'DOCK', using the UP and DOWN arrows to select each letter, and the RIGHT arrow key to advance to the next character position. If you make a mistake and select an incorrect character, simply use the LEFT arrow key of the keypad to backspace the cursor and correct the entry.
- 5. Press error to confirm the name.
- 6. The field highlight will advance to the symbol field. Press error to access the waypoint symbol page.
- 7. Use the low keypad to highlight the ANCHOR symbol.
- 8. Press eres to confirm the symbol.
- 9. Press error again to confirm the 'DONE?' prompt and save the waypoint.

The waypoint is now stored in memory. Note that waypoints may also be created graphically from the map display and by manually entering position coordinates. Both of these techniques are described in the reference section of the manual and/or on your GPSMAP 130 quick reference guide. To continue our tour, let's move on to the map page. The GPSMAP 130's **map page** combines digital chartplotting with a user-selectable display of navigation data and a built-in worldwide database to 64 nm. It will also be the page you use most to create and edit waypoints and routes. Before we take off on our practice route, let's take a brief look at its various features and displays.



The **map display**, located in the middle of the page, shows your boat as a triangle marker on an electronically generated chart, along with geographic names, markers and buoys that are provided by the G-chart cartridge you're currently using. It also displays your track, routes and nearby waypoints. An on-screen **cursor** lets you pan to other map areas, determine the range and bearing to a position, and perform various waypoint and route functions.

The **data window**, located at the top of the page, provides a user-selectable display of various navigation data, including course, speed over ground, and the bearing and distance to the cursor or a particular waypoint. The status bar, located at the bottom of the page, displays the current map scale setting, as well as the status information described on page 17.



- **A.** To select an on-screen waypoint, simply move the cursor over the desired waypoint. The waypoint/navaid name and position, along with the bearing and distance from your present position, will be displayed.
- **B.** The map page can also be configured to display additional data fields and a graphic course deviation scale or compass. See page 26 for more on map options.



- **A.** Whenever the cursor is active, the bearing and distance of the cursor from your present position will appear in a pop-up data window.
- **B.** To remove the cursor and recenter your vessel on the map, press the QUIT key.

# Using the Map Cursor

Working from the map page is a simple process that centers around the use of the cursor. Controlled by the tevpad, the cursor is an important tool that can be used to pan to other map locations, mark and edit waypoints and routes, and review position data of on-screen navaids and waypoints.

To get a feel for using the map page and using the cursor, try the following exercise:

- 2. Use the DOWN arrow of the rew keypad to move the cursor down to the first lat/lon grid south of your boat's position.
- 3. Using the keypad to move the cursor, try following the outline of the lat/lon grid closest to your boat. Notice how another data field appears at the top of the page, showing the bearing and distance from your boat to the cursor, along with the lat/lon of the cursor.
- 4. Press the our key to remove the cursor and recenter your boat on the map display.

As you become more familiar with the cursor, you'll see that the map display actively scrolls or 'pans', letting you explore areas around the world (even outside of your current G-chart<sup>TM</sup> coverage) and create waypoints and routes. Wherever you move the cursor, you'll always be just one every keystroke away from returning the map to your present position.

Now that you have a feel for how the cursor works, let's move on and see how the GPSMAP 130 works on the water. To help you practice using the map page and other features, we've stored a practice route in the receiver's permanent memory, so you can see exactly what you'll experience when you're navigating with your new GPS chartplotter.

# Going to a Destination

GPS is all about marking positions as waypoints and navigating to them using the receiver's steering guidance and map displays. We've already seen how to use the we've already seen how to use the we've already seen how to use the we've already seen how to use to store our present position, so it's time to move on to the fun part—going to a destination. The ever key, located on the left side of the keypad above the ever key, is the primary tool used to select a destination waypoint or a route to navigate. The ever key can be used in three primary ways:

- Pressing for once displays a list of all waypoints in memory, from which you can select a single destination waypoint.
- Pressing followed by the first key provides a list of GOTO options that lets you start a TracBack<sup>TM</sup> route, select a destination waypoint from the nearest waypoints list, select a stored route to navigate, or cancel the current GOTO destination.
- Pressing and twice allows you to graphically select an on-screen waypoint, navaid or cursor position as a destination directly from the map display.

For our simulated trip, we're going to select the preprogrammed tour route (the second method), which will automatically place our vessel at the first route way-point. This will also give us an idea of how the way key is used throughout the GPSMAP 130 system to provide context-sensitive options and functions. Let's give it a try by activating the practice route stored in memory for navigation:

- 1. Press error. The waypoint list page will appear (if we were selecting a single waypoint to navigate to rather than a route, we would highlight the waypoint and press error).
- 2. Press were to display the context-sensitive options available for the GOTO function.
- 3. Use the 🌑 keypad to highlight the 'Select Route?' option. Press 💷 to confirm.
- 4. The select route page will appear, with the 'GPSMAP TOUR' route highlighted.
- 5. Press IRE. The map page will reappear and display five waypoints chained together in a simple route, with your boat at the first route waypoint.



- **A.** Pressing GOTO once displays a list of all waypoints stored in memory. To pick a destination, select the desired waypoint and press EDIT/ENTER.
- **B.** The GOTO options page allows you to either start a TracBack route back home, select a destination from the nearest waypoints list, or select a route to navigate.



- **A.** To enter a boat speed or define the simulated course, highlight the 'Setup Simulator?' option and press EDIT/ENTER.
- **B.** Enter a boat speed of 60 knots to begin the tour. This will allow you to complete the Getting Started tour in 10-15 minutes.

A **data field** at the top of the page will now display the bearing and distance to the second route waypoint. To get started, let's enter a speed for our vessel, which we can do from the 'Setup Simulator?' listing on the options page. The **setup simulator page** is also available from any other page in the main page sequence.

# To enter a boat speed:

1. Press the **MENU** key to display the map options page.

2. Use the 🌑 keypad to select the 'Setup Simulator?' option and press 🕅.

3. Once the setup simulator page appears, press 🛲 to access the SOG field.

4. Use the 🗭 keypad to enter a speed of 60 knots.

5. Press ERER to finish, and PAGE to return to the map display.

Once a speed has been entered, you'll notice that the map will begin to move slowly, keeping your boat centered on the display. To get a better view of what's going on, zoom in to a closer map scale.

# 1. Press the DOWN arrow of the $\clubsuit$ key to select the 16 nm scale.

You'll now have a clearer picture of the route we are navigating, along with an outline-only presentation of the surrounding shoreline. Because the usable range of the built-in database is only valid to 64 nm scale, we no longer have full cartography available. Keep in mind that whenever you do exceed the usable range of the built-in database or the G-chart cartridge in use, the range field will display 'OVR ZM' or 'NO MAP' to indicate that you should exercise extreme caution using the cartography data. See page 25 and 66 for more information on map scales and using G-chart detailed cartography.

Now that we're zoomed in a little closer to our route, we can pan ahead of our vessel with the cursor to review and create on-screen waypoints and navaids. Try moving the cursor to select the 'TOUR3' waypoint— just use the  $\bigoplus$  keypad to move the cursor as close as possible to the waypoint (to move the cursor in small increments, try a series of short key presses).

Once the cursor is over the TOUR3 waypoint, you'll notice that the waypoint symbol and name will become highlighted, and the data field at the top of the page will display the waypoint name, the range and bearing from your present position, and the coordinates for the waypoint.

WAYPOINT TOUR3 N 35°01.287' W076°25.085' GPSMAP TOUR
REF WPT
BRG 095% DIS 922%
Done?

To review the waypoint page for a selected waypoint:

1. Press the ENTER key.

2. To return to the map page, press **ENTR** again.

The cursor can also be used to create new waypoints right from the map display.

#### To create a new waypoint using the cursor:

- 1. Use the keypad to move the cursor as close as possible to the following position: N 35° 02.129'; W 076° 26.106' (use the data window to verify the cursor position).
- 2. Press the ENTRy key to capture the cursor position.
- 3. Use the 💭 key to highlight the waypoint symbol field.
- 4. Press effect to access the symbol page.
- 5. Press the DOWN arrow of the keypad twice to select the wreck symbol.
- 6. Press EVER to confirm, and EVER again to finish.



- **A.** Waypoints can be created from the map display by moving the cursor to the desired position and pressing the EDIT/ENTER key.
- **B.** The create new waypoint page will automatically assign the next available three-digit number as the default waypoint name. If you are creating a waypoint at an on-screen navaid, the navaid icon and name will be used as the default symbol and comment.



- **A.** In this example, our boat is off course to the left by about 1/16th of a mile (the base of the highway map is equal to the scale selected at the bottom right of the page). To get back on course, steer right.
- **B.** In this example, our boat is off course to the right. To get back on course, steer left. A digital readout of your exact crosstrack error can be displayed in any of the six data fields (see page 29).

Now that we're navigating to an actual destination, let's move on to the next page of the GPSMAP 130 system, the **navigation page**:

1. Press the PAGE key.



The navigation page provides graphic steering guidance to your destination. The **bearing (BRG)** and **distance (DIS)** to the destination, with your current **course (COG)** and **speed over ground (SOG)**, are displayed at the top of the page, along with a graphic compass to indicate your cardinal heading. The estimated time enroute (ETE) and velocity made good (VMG, or the rate you are closing in on your destination) are displayed at the bottom of the page.

As you head toward the destination, the middle section of the page gives you visual guidance to your waypoint on a **graphic highway**, which displays the route and nearby waypoints on screen. The moving arrow below the highway always points to the destination waypoint relative to the direction you're moving. The line down the center of the highway represents your desired track, while the bottom of the page provides a graphic indication of your **crosstrack error** (the distance and direction you are off course) according to the scale at the bottom right of the page.

Whenever the GPSMAP 130 is in simulator mode, you can adjust your speed and course from the navigation page using the keypad. As you head toward each waypoint in the tour route, try adjusting your boat speed and course to get a feel for how the highway works.

# To adjust the simulated boat speed:

1. Press the UP arrow of the keypad to increase the speed in 5 knot/kph/mph increments. Press the DOWN arrow to decrease the speed in the same increments.

# To steer the boat:

# 1. Press the LEFT and RIGHT arrows of the 🌑 keypad.

Notice that as you get off course, the highway and waypoint pointer move to give you graphic guidance to get back on course. The base of the highway display also serves as a graphic course deviation indicator (CDI), relative to the scale setting shown at the bottom right of the page. The scale setting represents the total distance (or the width) of the base of the highway display. The default CDI/graphic highway setting is 1/4 nm, but can be set for a 1/2-, 1-, 2- or 4-nm range.

# To change the CDI scale/highway display:

# 1. Press the 🖨 key in either direction (up to increase, down to decrease the scale).

The navigation page data fields may also be configured to display any of ten different navigation values. Let's change the VMG field to crosstrack error to provide a digital readout of the distance we're off course.

# To change a data field:

- 1. Press the MENU key to display the position page options.
- 2. Highlight the 'Change Data Fields?' option and press [###]. The field highlight will now appear in the top-left data field (the BRG field).
- 3. Use the ) keypad to move the field highlight to the VMG field and press
- 4. Highlight the 'XTE' option and press 🛲 , and press our to finish.



- **A.** To reset the simulator to steer the desired course automatically, select the 'Auto COG' setting from the options page.
- **B.** The CDI scale perspective can be set to a 1/4-, 1/2-, 1-, 2-, or 4-nm/mi/km range with the ZOOM keys.



- **A.** To stop navigating the active route, select the "Deactivate Route?" option and press EDIT/ENTER.
- **B.** Use the left arrow key to clear the SOG field and press EDIT/ENTER to confirm.

Now that you've seen the four main pages, let's review the **active route page**, which appears in the main page sequence whenever you are navigating a route:

# 1. Press the PAGE key.

The active route page shows each waypoint of the active route in sequence, with the waypoint name, distance and estimated time enroute to each waypoint displayed. As you navigate the route, the active route list will be automatically updated, indicating the next destination waypoint.

The active route page also provides quick access to many route activation, editing and copying functions you'll use most often, like inverting and deactivating the active route. Let's go ahead and deactivate the active route.

# To deactivate the active route and stop navigation:

1. Press the MENU key.

2. Highlight the 'Deactivate Route?' option.

3. Press ENTER to confirm.

# To reset the boat speed to zero:

1. Press the MENU key.

2. Highlight the 'Setup Simulator?' option.

3. Press Enter

4. Press EVER to access the SOG field.

5. Press the LEFT arrow of the 🜑 keypad to clear the speed entry.

6. Press Enter .

As you've seen, the GPSMAP 130's main pages provide vital status, position, navigation and map information. The last page we'll cover in the tour is the **main menu** page, which provides access to the GPSMAP 130's waypoint, route and planning functions, as well as various operational and navigation setup features. The main menu is available from any page, and is accessed through the well.

#### To access the main menu page:

1. Press the MENU key twice.

The main menu page's 11 submenus are divided into categories by function. You can select a particular submenu by simply highlighting the desired option and pressing and. To get a feel for how the main menu page works, let's clear out the track log we've created during our simulated tour. This will ensure that you have a clean slate once you start navigating in your home waters.

# To select the track submenu:

1. Highlight the 'Track' menu option and press [FFF].

The track log page allows you to specify whether to record a track plot and define how it is recorded. It also provides both an indicator of the total memory used and the individual functions to clear the track log and start a TracBack route.

# To delete the track log:

1. Highlight the 'Delete Track' option and press 🛲. A confirmation page will appear.

2. Highlight the 'Yes' prompt and press 🛲 to confirm.

3. Press PAGE to return to the main page sequence.

Congratulations! You've now gone through the basic operation of the GARMIN GPSMAP 130. Your new digital chartplotter is a powerful tool with many advanced features not covered in the Getting Started tour. For detailed instructions on using these features or performing a specific task, please refer to the quick reference guide or the appropriate reference section of this manual.



- **A.** The GPSMAP 130's track page lets you clear the track log and start a TracBack route.
- **B.** To delete the track log, confirm the warning page by highlighting the 'YES' prompt and pressing EDIT/ENTER.





# To turn the GPSMAP 130 off:

1. Press and hold the 👀 key for about 3 seconds, until the screen is blank.

Thank you for choosing the GARMIN GPSMAP 130 navigation system. We hope that it will be a useful tool for you wherever you travel.

#### **Status Page**



The GPSMAP 130 **status page** provides a visual reference of various receiver functions, including current satellite coverage, receiver operating mode and current receiver accuracy. The status information will give you an idea of what the receiver is doing at any given moment.

The **sky view** and **signal strength bars** give you an indication of what satellites are visible to the receiver and whether or not they are being tracked. The signal strength is shown on a bar graph for each satellite, with the satellite number below. When a satellite is visible but not being tracked, the strength bar will not be shown and the sky view indicator will not be highlighted.

The sky view shows a bird's-eye view of the position of each satellite relative to the receiver's last known position. The outer circle represents the horizon (track up), the inner circle 45° above the horizon, and the center point a position directly overhead. Use the sky view to determine if there are obstructions shading your reception of GPS signals.



- A. Whenever the GPSMAP 130 is searching for satellites, no signal strength bars will appear.
- B. Once the receiver has found the satellite(s) indicated, a hollow signal strength bar will appear. After satellite data has been collected, the signal strength bars will become solid.



- **A.** The status bar at the bottom of the page displays important status, alarm and map scale information. It also provides on-screen user and message prompts.
- **B.** The status bar will display an anchor symbol or 'PRX' icon whenever the anchor drag alarm or proximity alarm has been triggered.

# Receiver Status, EPE & DOP

Receiver status is indicated at the top of the page, with the current **estimated position error** (EPE) and **dilution of precision** (DOP) to the left of the sky view. DOP is an indication of satellite geometry quality measured on a scale of one to ten (lowest numbers the best, highest numbers the poorest). EPE uses DOP and other factors to calculate a horizontal position error in feet or meters. The status field will show one of the following conditions:

- Searching the Sky— the receiver is looking for any satellites.
- **AutoLocate** the receiver is is looking for any satellite whose almanac has been collected. This process can take up to five minutes.
- **Acquiring Satellites** the receiver is looking for and collecting data from satellites visible at its last known or initialized position, but has not collected enough data to calculate fix.
- **2D Navigation** at least three satellites with good geometry have been acquired and a 2 dimensional position fix (latitude and longitude) is being calculated. '2D Differential Navigation' will appear when you are receiving DGPS corrections in 2D mode.
- **3D Navigation** at least four satellites with good geometry have been acquired and your position is now being calculated in latitude, longitude and altitude. '3D Differential Navigation' will appear when you are receiving DGPS corrections in 3D mode.
- **Poor GPS Coverage** the receiver is no longer tracking enough satellites for a 2D or 3D fix.
- **Receiver Not Usable** the receiver is unusable, possibly due to incorrect initialization or abnormal satellite conditions. Turn the unit off and back on to reset.
- Simulating Navigation— the receiver is in simulator mode.

#### **Status Page Options**



The GPSMAP 130's status page features a context-sensitive options page that provides access to functions and features relating to the status page.

#### To display the status page options:

1. Press Menu

#### To select a menu option:

1. Highlight the desired option and press

The following options are available:

- **Initialize Position?** allows you to initialize the receiver graphically or by text. See pages 1-2 for instructions on initialization.
- Start AutoLocate?— allows the receiver to locate your position automatically.
- **Track Up/North Up SkyView?** allows you to select between a north up or track up sky view display.
- **Setup Simulator?** allows you to define speed, course and position values while in simulator mode. See the Getting Started Tour for more on using simulator mode.



- A. Whenever the GPSMAP 130 is in simulator mode, the 'Setup Simulator?' option will appear on all the main pages.
- **B.** The setup simulator page allows you to define your speed and course over ground, as well as your postion and altitude. The 'Auto COG' option will automatically steer the desired course to your destination. Your speed and course can also be selected from the navigation page using the rocker keypad (see page 13).



The trip odometer can be reset from the position page options window. To reset the odometer, select the 'Reset Trip Distance?' option and press EDIT/ENTER.





The GPSMAP 130 position page shows you where you are, what direction you are heading and how fast you are going. The top of the page features a graphic compass tape to indicate the direction you're heading (while you're moving), and four user selectable data fields: course over ground (COG), speed over ground (SOG), distance travelled (TRP) and altitude (ALT). The bottom half of the page displays your present position's coordinates, along with the time of day as calculated using GPS satellites. The status bar at the bottom of the page indicates position fix status, and is described in detail on page 18.

The units of measure for speed, distance, position and altitude are all userselectable through the navigation setup option on the main menu page. The time of day, shown in UTC (Universal Time Coordinated, or Greenwich Mean Time) may be set to display in a 12- or 24-hour time format (with a local offset) through the system setup option on the main menu page.

# **Position Page Options**

The GPSMAP 130's position page features a context-sensitive options page that provides access to functions and features relating to the position page.

To display the position page options:

1. Press Menu

#### To select a menu option:

1. Highlight the desired option and press 📰.

The following options are available:

- Reset Trip Distance?— resets the trip odometer (TRP) field to zero.
- **Change Data Fields?** allows you to choose the data displayed in the four user-selectable data fields. Five data types are available:
  - SOG— speed over ground
  - COG— course over ground
  - TRP— distance travelled
  - ALT— altitude
  - VDC— DC voltage

To change a data field:

- 1. Highlight the 'Change Data Fields?' option and press 🛲
- 2. Move the field highlight to the field you want to change and press
- 3. Select the desired data field option and press
- Restore Defaults?— resets all data fields to the factory settings.
- **Setup Simulator?** allows you to define speed, course and position values while in simulator mode. See the Getting Started Tour for more on using simulator mode.



- **A.** The four data fields at the top of the position page can be changed by selecting the 'Change Data Fields?' option.
- **B.** Each data field can be set to display speed over ground, course over ground, distance travelled, altitude or DC voltage.



- **A.** Use the cursor to pan ahead to other map areas. The map display will automatically scroll forward when you reach the edge of the map.
- **B.** To select or 'highlight' an on-screen navaid or waypoint, simply move the cursor over the waypoint symbol. The cursor will 'snap' to the waypoint, and display its name and position in the data field.

#### GPSMAP 130 Map Page



The GPSMAP 130's map page provides a comprehensive display of electronic cartography, plotting and navigational data. The **map display** shows your boat on a digital chart, complete with geographic names, navaids, depth contours and a host of other chart features. It also plots your track and displays any routes and waypoints you create. An on-screen cursor lets you pan and scroll to other map areas, determine the distance and bearing to a position, and perform various route and waypoint functions.

The **data window**, located at the top of the page, provides a user-selectable display of your current course and speed over ground, along with the bearing and distance to a destination waypoint. Whenever the cursor is active, an additional data window will appear below to indicate the position, range and bearing to the cursor or a selected waypoint or navaid. Each data field may be configured to display any one of ten data options. The data window may also be changed to display additional data fields, a graphic compass tape, or a CDI scale. The **status bar** at the bottom of the page displays the map scale currently in use.

#### **Map Modes**

The map display uses the cursor keypad and a set of hard keys to control most map display functions. The  $\clubsuit$  keys, combined with the  $\textcircled$  keypad, let you select zoom ranges and move the cursor. Two basic map operating modes, position mode and cursor mode, determine what cartography is shown on the map display. Position mode pans the cartography to keep the present position marker within the display area, while cursor mode pans the cartography to keep the cursor within the display area.

The GPSMAP system will always power up in the position mode, with your vessel centered on the map display.

- Whenever sufficient map coverage is not available to keep the boat centered, the boat icon will move toward the edge of the display.
- If the boat icon attempts to go off the display, the zoom level may need to be adjusted to keep cartography on screen.

Whenever the  $\bigoplus$  keypad is pressed, the GPSMAP 130 will enter cursor mode. In cursor mode:

- The cursor can be moved over the map display using the  $\bigcirc$  keypad.
- Whenever the cursor reaches the edge of the display, the map will scroll forward under the cursor. Keep in mind that the boat icon will move with the map scrolling and may go off the display screen (you may not be able to see your present position).
- When the cursor is stationary, a fixed coordinate position will appear in the position field. Note that the distance and bearing will change as the boat's position changes.
- Whenever you zoom in cursor mode, the cursor will be centered on screen.
- To return to position mode, press the our key.



- A. Position mode on inland water cartography.
- **B.** Cursor mode on inland water cartography.



- **A.** To create a new waypoint at the cursor, move the cursor to the desired position and press EDIT/ENTER.
- **B.** The create new waypoint page will appear, where you may change the waypoint name, symbol and comment before saving the waypoint.

# Using the Cursor

The cursor allows you to pan away from your present position and scroll to other map areas around the world (even outside of your current G-chart<sup>M</sup> coverage). As you pan past the edge of the current map display, the screen will actively scroll forward to provide continuous map coverage.

# To move the cursor:

# 1. Press the 🌑 keypad to move the cursor in an up, down, left or right direction.

As you move the cursor, the distance and bearing from your present position to the cursor will be displayed in the data window, along with the cursor's position coordinates. Keep in mind that when the cursor is stationary, the distance and bearing from your present position will change as your boat moves. The cursor may also be used to 'snap' to on-screen waypoints and navaids, allowing you to review a selected position directly from the map display.

# To select an on-screen waypoint or navaid with the cursor:

- 1. Use the keypad to move the cursor to the desired waypoint or navaid (if there are several waypoints grouped closely together, zoom in closer for a better view).
- 2. When a waypoint or navaid is selected, it will become highlighted on screen, with the name and position displayed.

# To eliminate the cursor and re-center your position on-screen:

1. Press the our key.

The cursor may also be used to create new waypoints directly from the map.

# To create a waypoint with the cursor:

1. Use the () keypad to move the cursor to the desired map position.

- 2. Press Enter
- 3. Press even to confirm the new waypoint.

# **Selecting Map Scales**

The map display has 16 available range scales from 1/8th to 4096 n.m. (1/4 to 7500km). The map scale is controlled by the  $\clubsuit$  keys, with the current scale displayed at the bottom of the data window.

#### To select a map scale:

# 1. Press the up $\clubsuit$ key to zoom out and the down $\clubsuit$ key to zoom in.

The GPSMAP 130's system has a built-in worldwide database to 64 n.m.(see Appendix D for a built-in coverage map), with more detailed coverage available through the use of G-chart<sup>TM</sup> data cartridges (see Section 10 for installing and using G-chart<sup>TM</sup> cartridges). The GPSMAP 130 will display cartography as long as there is chart information available for the range you've selected. Map coverage will conform to the following conditions:

- When the selected zoom range is covered by either the internal database or a G-chart data cartridge, cartography will be displayed.
- When the selected zoom range is covered by both the internal database and a G-chart cartridge, cartography will be displayed using the data with the best resolution.
- When the selected zoom range exceeds the resolution of the chart in use by up to two settings, overzoom cartography will be displayed. The display will not show any filled landmass areas, and an 'Ovr Zm' warning will appear in the scale field. The lat/lon grid will also be turned on regardless of the map configuration setting.
- When the selected zoom range exceeds the resolution of the chart in use by more than two settings, all cartography will be replaced by a track plot display, and a 'No Map' warning will appear in the scale field. The lat/lon grid will be displayed regardless of the map configuration setting. Additional caution should be used while navigating in track plot mode.



- **A.** Whenever the selected map scale exceeds the resolution of the chart by up to two settings, an 'Ovr Zm' warning will appear in the scale field.
- **B.** Whenever the selected map scale exceeds the resolution of the chart by more than two settings, a 'No Map' warning will appear in the scale field.



- **A.** The map options page provides access to all map configuration, page display and data field options.
- **B.** The 'Maximize Map?' option will eliminate the data fields and show full-screen cartography.

# Map Page Options

The GPSMAP 130 map page is designed to be a flexible tool that can be custom-tailored to your exact navigation needs. The map options page provides access to many of the features and functions that will help you configure the map page to your own preferences.

# To display the map page options:

1. Press Menu .

#### To select a menu option:

1. Highlight the desired option and press Even.

The following options are available:

- **Maximize/Normal Map?** allows you to select between a full-screen map display or the default map display with data window.
- **Map Outlines Off/On?** allows you to specify whether coverage outlines for G-chart cartography are displayed or not. The default setting is on.
- **Measure BRG/DIS?** allows you to measure the bearing and distance between any two points on the map display.

#### To measure the BRG/DIS between two points:

- 1. Highlight the 'Measure BRG/DIS?' option and press (IMM). An onscreen pointer will appear on the map display at your present position.
- 2. Move the cursor to the desired reference point (the point that you want to measure from) and press .
- 3. Move the cursor to the point that you want to measure to. The bearing and distance from the reference point will be displayed at the bottom left of the data window.
- 4. Press the our key to finish.
• **Configure the Map?**— allows you to determine what chart features are displayed on a particular map scale to prevent excessive clutter. The map configuration page features an on/off grid with a list of chart features down the left side. The zoom scales are displayed across the top of the grid with the chart scale currently in use also indicated. The far-left scale setting represents all map scales 64 nm and above. A check mark in a grid box indicates that the chart feature listed will be displayed at the corresponding scale.

Individual grid boxes may be turned on and off through a popup scale window, while entire rows may be controlled by using the map configuration options page (accessible through the **Deriv** key).

### To use the map configuration grid:

- 1. Use the keypad to select the desired map item and press . A popup window will appear with the current settings displayed.
- 2. Use the 🜑 keypad to highlight the scale you want to change.
- 3. Press Entry to change the on/off setting.
- 4. Press our to finish.

### To turn an entire row on or off:

1. Use the 💭 keypad to select the desired map item.

2. Press the MENU key.

3. Select the 'Enable Row?' or 'Disable Row?' option and press 🛲 .

The map configuration page also allows you to set the moving map display to a North Up, Track Up or Desired Track Up orientation.

## To change the map orientation:

1. Use the 🌑 keypad to highlight the Orientation field and press 🛲 .

2. Select the desired setting and press 💵 .



- **A.** The map configuration grid allows you to define what items appear on the display at each map scale.
- **B.** To turn an entire row on for the selected map item, highlight the 'Enable Row?' option and press EDIT/ENTER.



- **A.** To calibrate the map, highlight the 'Calibrate the Map?' option and press EDIT/ENTER.
- **B.** A satellite icon will remain on the map to indicate the GPS position, while the boat marker will reflect the calibration changes.

# CAUTION!

The map calibration function should never be used to attempt corrections to Selective Availability errors. The map configuration options page also features a map calibration function that allows you to calibrate the map display with your exact physical surroundings or correct data from older charts. Before using the map calibration function, check to make sure that your map datum selected on the GPS matches the datum on the chart you are using (see page 61). To calibrate the map display, you must know exactly where you are, and understand that the correction is generally valid only in a limited range from the point of correction.

Map calibration should only be performed while the vessel is not moving, and should never be used to attempt SA corrections, which can degrade accuracy up to 330' (100 meters). The maximum correction is 16,400 feet (5000m).

## To calibrate the map:

- 1. Select the 'Calibrate the Map?' option and press ERE.
- Use the keypad to move the arrow cursor from the satellite position (indicated by the satellite icon) to your exact position. The bearing, distance and position will be indicated in the data window.
- 3. Press error to confirm the calibration offset.

The next option available from the map configuration page is the set map colors option, which allows you to define the fill color (grayscale) of the land and water used on the map display. Three options are available: no color (no fills for land or water), gray land/white water (the default setting), and white land/gray water.

## To select a map colors option:

- 1. Select the 'Set Map Colors?' option and press Err.
- 2. Highlight the desired map color option and press Ener.

The map configuration options page also features a 'restore defaults' function that can be used to quickly restore all map configuration options to the factory settings.

### To restore the map configuration options to the factory defaults:

1. Highlight the 'Restore Defaults?' settings and press 🛲 .

- Setup Page Display?— allows you to specify the number of fields displayed in the data window section of the map page. A graphic compass tape or CDI scale may also be displayed. The following options are available:
  - 2 Fields

• 2 Fields & Compass

- 2 Fields & CDI
- 4 Fields & Compass
- 6 Fields
- 6 Fields & CDI

- 4 Fields
- 4 Fields & CDI
- 6 Fields & Compass
- 8 Fields

### To select a page display option:

1. Highlight the 'Setup Page Display?' option and press **EVER**.

2. Select the desired option and press ERE.

• Change Data Fields?— allows you to specify the data displayed in each data field used on the map display. The following options are available:

- BRG- bearing to active wpt DIS- distance to active wpt
- SOG- speed over ground
- COG- course over ground • ETE- estimated time enroute • ETA- estimated time of arrival
- XTK- crosstrack error
- VMG- velocity made good • WPT- active wpt name
- TRN- turn angle to wpt

### To change a data field:

1. Highlight the 'Change Data Fields?' option and press

2. Move the field highlight to the desired field and press EVER.

3. Select a data field option and press **ERE**.

- Restore Defaults?— resets all map page options (except map configuration options, see pages 27-28) to the factory settings.
- Setup Simulator?- allows you to define speed, course and position values while in simulator mode. See the Getting Started Tour for more on using simulator mode.



- **A.** The map page can be configured to display a variety of navigation data.
- **B.** Each data field can be set to display one of ten data options.



The navigation page can be configured to show the active waypoint, all route waypoints and/or nearby waypoints on the graphic highway.

#### **GPSMAP 130 Navigation Page**



Whenever a GOTO, MOB, TracBack or route has been activated, the GPSMAP 130 will provide digital and graphic steering guidance to the destination with the navigation page. The top half of the nav page features four user-selectable **data fields** that display the bearing (BRG) and distance (DIS) to waypoint, along with your current course (COG) and speed over ground (SOG). In addition, there's a moving compass tape to indicate the direction you're heading. Two additional data fields at the bottom of the page show the estimated time enroute (ETE) and velocity made good (VMG) to your destination.

The middle section of the screen provides visual guidance to the waypoint on a **graphic highway** display. The line down the center of the highway represents your desired track, while a graphic indication of the distance and direction you are off course is shown on a scale at the bottom right of the page (the selected scale represents the distance from side to side). The **arrow pointer** below the highway always points to the destination waypoint relative to the direction you are moving.



As you head toward your destination, the highway perspective will move to indicate your progress to the waypoint and which direction you should steer to stay on course. If you are navigating a route, the navigation page will show each route waypoint in sequence, with the active leg indicated by the white portion of the highway. Nearby waypoints not in the active route will also be displayed. The highway perspective/CDI scale may also be zoomed in or out to display a larger or smaller view of the highway. Five settings are available from 1/4 to 4 nm, with a default setting of 1/4 nm.

# To change the highway perspective/CDI scale:

1. Press the up or down arrow of the  $\clubsuit$  key to select the desired setting.

# Navigation Page Options

The GPSMAP 130's navigation options page allows you to define the nav data fields and select what waypoints are displayed on screen.

# To display the navigation page options:

1. Press Menu

## To select a menu option:

1. Highlight the desired option and press



- **A.** To change the CDI scale perspective, press the ZOOM keys.
- **B.** The navigation options page lets you set up the navigation page to your own preferences.



- A. Ten data options are available for each data field on the navigation page. The digital crosstrack error option is especially useful to display the exact distance you are off course in feet/miles or meters.
- **B.** To select what waypoints appear on the graphic highway, highlight the desired setting and press EDIT/ENTER.

The following options are available for the navigation page:

- **Change Data Fields?** allows you to define the data displayed in any of the six user-selectable data fields. Ten data options are available:
  - BRG– bearing to active wpt DIS– distance to active wpt
  - SOG– speed over ground COG– course over ground
  - ETE– estimated time enroute ETA– estimated time of arrival
  - XTK– crosstrack error
- VMG- velocity made good
- TRN– turn angle to wpt
- CTS- course to steer

# To change a data field:

- 1. Highlight the 'Change Data Fields?' option and press ERT.
- 2. Highlight the field you want to change and press 🛲 .
- 3. Select the desired data field option and press ERTE .

• **Configure Highway?**— allows you to select what waypoints are shown on the highway display. Four options are available:

- Nav & Nearest Waypoints- all route and nearest waypoints displayed
- Nav Waypoints— only waypoints in the active route will be displayed
- Active Waypoint- only the active waypoint will be displayed
- No Waypoints— no waypoints will be displayed

## To configure the highway display:

1. Highlight the 'Configure Highway?' option and press ERE .

2. Select the desired option and press ENTR.

- Restore Defaults?— resets all navigation page options to the factory settings.
- **Setup Simulator?** allows you to define speed, course and position values while in simulator mode. See pages 4-16 for more details on using simulator mode.
- **Auto COG?** allows you to reset automatic steering while simulating navigation and cancel any course adjustments made with the  $\bigoplus$  keypad.

## Main Menu Page

The GPSMAP 130's main menu page provides access to various waypoint, system, navigation and interface management and setup menus. The main menu page is available from any page in the GPSMAP 130's system, and is accessed through the reservence key.

	MAIN MENU
Ľ	earest Waypoints
P	roximity Waypoints
c	reate Waypoint
۷	aypoints (
R	outes
Т	rack
Т	rip & Fuel Planning
S	ystem Setup
N	avigation Setup
Т	imers & Alarms
Ir	put/Output
SI	IM

#### To access the main menu page:

1. Press MENU twice.

The 11 submenus are divided into categories by function.

### To select a submenu from the main menu page:

1. Highlight the submenu you want to view and press

For specific instructions on using a submenu, see the waypoints, route or setup sections of this manual.



- **A.** The waypoint category options on the main menu page are described in the Waypoints section on pages 34-42.
- **B.** The routes category options are described on pages 47-54.



- **A.** The mark key is used primarily to mark your present position, but it can also be used to mark the cursor or a navaid position from the map page.
- **B.** The mark position page also allows you to add the new waypoint to the end of any route. If you're heading out without a planned route, you can create a series of waypoints along the way with the mark key and save them to an open storage route. When you're ready to head back, simply invert the route to get back (see page 51).

# Creating and Using Waypoints

The GARMIN GPSMAP 130 stores up to 250 alphanumeric waypoints with a user-defined icon and comment available for each waypoint. Waypoints can be created using three basic methods:

- **Key-** used primarily for marking your present position, the **Key** also provides options that allow you to select a map or navaid position from the map display.
- **Graphically–** allows you to define a new waypoint position from the map display using the cursor.
- **Text Entry** allows you to enter a new waypoint's position coordinates manually (from a chart, etc.) or by referencing it's bearing and distance from a stored waypoint or your present position.

# Mark Key

The GARMIN GPSMAP 130's we key lets you quickly capture your present position— or cursor or navaid position— in order to create a new waypoint. You must have a valid position fix to mark your present position.

#### To mark your present position:

- 1. Press the Key. The mark position page will appear, with a default three-digit name for the new waypoint.
- 2. To accept the waypoint with the default name, symbol and comment (the date and time of creation), press error to confirm the 'Done?' prompt.
- 3. To enter a different name, symbol or comment, highlight the appropriate field and press the error key.
- 4. After entering and confirming your changes, move the field highlight back to the 'Done?' prompt and press area.



The mark key may also be used on the map page to mark the cursor position or an on-screen navaid. To mark a navaid, select the desired navaid with the cursor. The GPSMAP 130 will use the navaid text shown on the cartography as the default comment.

### To mark the cursor or navaid position with the wark key:

- 1. Use the  $\bigcirc$  keypad to move the cursor to the desired position or navaid.
- 2. Press the MARK key.
- 3. Highlight the 'Use Map Posn?' or the 'Use NAVAID Posn?' option and press 🛲 .
- 4. To accept the waypoint with the default name, symbol and comment (the date and time of creation), press **E** to confirm the 'Done?' prompt.
- 5. To enter a different name, symbol or comment, highlight the appropriate field and press the error key.
- 6. After entering and confirming your changes, move the field highlight back to the 'Done?' prompt and press [##].



- **A.** To create a waypoint at an on-screen navaid, move the cursor over the desired navaid.
- **B.** Press the MARK key and select the 'Use Navaid Posn?' option. Press EDIT/ENTER to finish.



- **A.** Once a position has been selected graphically, the create new waypoint page will appear. Here you can change the waypoint name, symbol or comment before saving the waypoint.
- **B.** To create a waypoint by text entry, start by entering the new waypoint's name.

# **Creating Waypoints Graphically**

Waypoints may also be quickly created from the map display, which allows you to 'point and shoot' at any map position to create a new waypoint.

### To create a new waypoint graphically:

1. Use the keypad to move the cursor to the desired map position. If you want to create the new waypoint at an on-screen navaid, highlight the navaid on the map display.

2. Press Enter .

- 3. To accept the waypoint with the default name, symbol and comment, press error are creating a waypoint at an on-screen navaid, the default symbol and comment will automatically reflect the selected navaid's name and symbol.
- 4. To change the name, symbol or comment, highlight the appropriate field and press 🛲.
- 5. After entering and confirming your changes, move the field highlight back to the 'Done?' prompt and press [1978].

# **Creating Waypoints By Text Entry**

Waypoints may also be created by manually entering a position's coordinates or referencing a stored waypoint through the 'Create Waypoint' submenu option on the main menu page.

#### To create a new waypoint by manually entering its coordinates:

- 1. Press were twice to display the main menu page.
- 2. Highlight the 'Create Waypoint' option and press **E**. The waypoint definition page will appear, with the next available waypoint number and the receiver's last known position as the default name and position.
- 3. Use the () keypad to enter the new waypoint name, icon, position and comment. Press enter the last character in each section.
- 4. When you have finished entering all your waypoint data, use the replace to highlight the 'Done' prompt and press eres.

## **Reference Waypoints**

A new waypoint may also be created without knowing position coordinates by entering its range and bearing from an existing waypoint or your present position. The GPSMAP 130 will then calculate the position coordinates for you, using the reference selected.

MAIN MENU
WAYPOINT
DIVE 💿
N 39°49.740' W092°32 189'
REF WPT
BAMP
BRG 148% DIS 0.22%
Done?
input/Output
SIM

To create a new waypoint using a reference waypoint:

- 1. Select the 'Create Waypoint' option from the main menu page and press 🛲 .
- 2. Enter the name, icon and comment for the new waypoint.
- 3. Highlight the reference waypoint field and press 🛲
- 4. Enter the name of the reference waypoint using the  $\textcircled$  keypad, or press  $\blacksquare$  to select the waypoint from the nearest list, waypoint list, or map display. Leave the reference field blank to use your present position.
- 5. Press even to begin entry of the bearing from your reference waypoint to the new waypoint position. Enter the bearing and press even .
- 6. Press 📾 to begin entry of the distance from your reference waypoint to the new waypoint position. Enter the distance and press 📾. The position for the new waypoint will automatically be calculated.



- **A.** Enter the bearing from the reference waypoint to the new waypoint in the 'BRG' field.
- **B.** Enter the distance from the reference waypoint to the new waypoint in the 'DIS' field.

7. Highlight the 'Done' prompt and press **ERE** to finish.



- **A.** The waypoint definition page will appear whenever a waypoint is selected from the map or a waypoint list.
- **B.** A 20-character custom waypoint comment may be assigned to every waypoint. The default comment is the date and time of creation.

# **Reviewing & Editing Waypoints**

Once you have created and stored a waypoint, it may be modified, reviewed, renamed or deleted at any time through the waypoint definition page. The waypoint definition page is available for any stored waypoint by highlighting the desired waypoint from the map display or selecting it from any waypoint list and pressing the set.

### To access the waypoint definition page:

1. Use the keypad to highlight the desired waypoint on the map display (or any waypoint list).

### 2. Press I to display the waypoint definition page.

From the waypoint definition page, you may change the waypoint symbol, position coordinates, or the waypoint comment for the selected waypoint.

### To change the waypoint symbol:

1. Highlight the waypoint symbol field and press EPER.

2. Use the 🐑 keypad to select the desired symbol and press 💷 to confirm.

### To change the position coordinates:

1. Highlight the coordinates field and press **EVER** .

2. Use the () keypad to edit the coordinates and press 🛲 to confirm.

#### To change the waypoint comment:

- 1. Highlight the comment field and press
- 2. Use the LEFT arrow of the 🔿 keypad to clear the comment field.
- 3. Use the 🜑 keypad to enter a comment (up to 16 characters).
- 4. Press ENTER to confirm.

## Waypoint Definition Page Options

The waypoint definition page also features an options page that allows you to edit the selected waypoint on the map display, rename the selected waypoint or delete the waypoint from memory.

## To display the waypoint definition page options:

1. Press the MENU key.

#### To review/edit the selected waypoint from the map display:

- 1. Highlight the 'Edit Wpt On Map?' option and press EPPER.
- The selected waypoint will appear on the map display, with the waypoint name and coordinates shown at the top of the map, along with the distance and bearing to the waypoint from your present position.
- 3. To move the selected waypoint's position, press 🛲 . A 'MOVE' label will now appear under the cursor arrow.
- 4. Use the to move the cursor arrow to the desired position. The cursor's coordinates, along with the distance and bearing from the waypoint's position, will be displayed at the top of the map display.
- 5. Press even to set the waypoint's new position, and even to return to the waypoint definition page.

## To rename the selected waypoint:

- 1. Highlight the 'Rename Waypoint?' option and press ERE.
- 2. Enter the new waypoint name and press ENTER.
- 3. Press effect to confirm the 'Yes' prompt.

## To delete the selected waypoint:

1. Highlight the 'Delete Waypoint?' option and press ERR.

2. Press ere to confirm.



- **A.** To review or edit a waypoint on the map display, select the 'Edit Wpt On Map?' option.
- **B.** To move the selected waypoint, press EDIT/ENTER. Use the arrow keypad to select the new position, and press EDIT/ENTER to finish.



#### **A.** The main menu page features four waypoint submenus.

**B.** The nearest waypoint list continuously updates to show the nine nearest waypoints to your present position.

# Waypoint Submenus

The GPSMAP 130's main menu page features four waypoint submenus that let you manage a large number of waypoints quickly and efficiently. The submenus also provide a continuously updated nearest waypoints list and a proximity waypoint alarm function that can be used to define an alarm circle around submerged hazards, shallow waters, etc.

# To access the main menu page/waypoint submenus:

## 1. Press MENU twice.

The first waypoint submenu is the **nearest waypoints list**, which shows the nine nearest waypoints that are within 100 miles of your present position. The nearest waypoints are continuously updated to your present position, and provide quick access to the closest points of safety in emergency situations.

## To scroll through and review the nearest waypoint list:

- 1. Highlight the 'Nearest Waypoints' option and press
- 2. Use the list in either direction.
- 3. Press even to review the highlighted waypoint.
- 4. To return to the waypoint list, highlight the 'Done?' prompt and press
- 5. The field highlight will automatically scroll to the next waypoint. If you want to review each waypoint, you can scroll through any waypoint list by pressing the EPER key repeatedly.

### To select a nearest waypoint as a GOTO destination:

1. Use the low key to select the desired GOTO waypoint.

2. Press GOTO, followed by ENTER.

### **Proximity Waypoints**

The **proximity waypoints list** lets you define an alarm circle around a stored waypoint position, and can be used to help you avoid reefs, rocks or restricted waters. Up to nine waypoints may be listed, with a maximum alarm radius of 99.99 nautical or statute miles or kilometers. If a proximity alarm circle overlaps with an existing alarm circle, a 'Proximity Overlap' message will appear each time the unit is turned on. If you enter an alarm circle overlap, you will only be alerted to the closest proximity waypoint.

#### To enter a proximity waypoint:

- 1. Highlight the Proximity Waypoint option and press EFF.
- 2. Use the 🗼 key to highlight the first blank waypoint field and press 🛲 .
- 3. Enter the name of the proximity waypoint using the () keypad, or press () to select the waypoint from the nearest waypoint list, waypoint list, or map display.
- 4. Press EVER to confirm. The distance field will now be highlighted.
- 5. Press Entry of the proximity radius.
- 6. Use the 🌑 keypad to enter a distance value (to 99.99 units) and press 🛲 .

#### To turn proximity alarms on or off:

- 1. Use the 🗼 keypad to highlight the alarms on/off field and press 🛲.
- 2. Select the desired setting and press [FFF].

#### To remove a proximity waypoint from the list:

1. Use the () keypad to highlight the waypoint to be removed.

#### 2. Press MENU .

- 3. Highlight the 'Clear Alarm?' field and press even.
- 4. To clear all proximity waypoints, select the 'Clear All' option and press ERE.



- **A.** Whenever you enter a proximity waypoint's alarm circle, a 'PRX' indicator will appear in the status bar (the alarms option must be set to the 'On' position). Once you've left the alarm circle, the proximity indicator will automatically reset.
- **B.** To clear all proximity waypoints, select the 'Clear All?' option from the proximity options page. Finish the deletion by confirming the 'Yes' prompt.



- A. The waypoints list displays all waypoints stored in memory in a two-column format. Temporary waypoints created by the TracBack feature are assigned a 'TXXX' name and a footprint symbol.
- **B.** The waypoints list options page lets you delete individual waypoints or the entire waypoint list.

# **Create Waypoint**

The third waypoint submenu available from the main menu page is the 'Create Waypoint' submenu, which allows you to create a new waypoint by manually entering coordinates. Instructions for using the create waypoint submenu are provided on page 36.

# Waypoint List

The last waypoint category available from the main menu is the **waypoints list**, which displays a master list of all waypoints currently stored in memory. From the waypoints list, you may review, edit, rename or delete individual waypoints; or delete all user waypoints. The total number of stored and available waypoints is displayed at the top of the waypoints page, with the stored waypoints arranged in numerical/alphabetical order and listed in two columns in the center of the page.

### To scroll through and review the waypoint list:

1. Highlight the 'Waypoints' option from the main menu page and press 📖 .

2. Use the list in the desired direction.

3. Press Error to review the highlighted waypoint.

4. Press even to return to the list.

### To delete an individual waypoint from the list:

1. Use the 🐑 keypad to highlight the waypoint to be deleted and press 🚥.

2. Press Enter .

3. Press the 🛲 key to confirm the deletion warning.

### To delete the entire waypoint list:

1. Press the MENU key to select the options window.

2. Highlight the 'Delete All User Wpts?' option and press 🕮 .

3. Use the () keypad to highlight the 'YES' prompt and press ERE to confirm.

# Going to a Destination

The GPSMAP 130 provides four ways to navigate to a destination: **GOTO**, **MOB**, **TracBack and route navigation**. The most basic method of selecting a destination is the GOTO function, which lets you select a waypoint as your destination and quickly sets a direct course from your present position. The correst leaves a direct course from your present position. The correst leaves and from a list of GOTO options. Pressing the correst leaves a list of all waypoints in memory, from which you can select a single destination waypoint.

### To activate a GOTO from the waypoint list:

1. Press the Goto key.

2. Select a waypoint and press EFFER.

# Selecting a GOTO Graphically

Pressing the **GOTO** key twice allows you to graphically select an on-screen waypoint, navaid or cursor position as a destination. A graphical GOTO may be used to select one of three options from the map display: an existing waypoint, an onscreen navaid, or a cursor position. If you are selecting a navaid or a new position as the GOTO destination, the GPSMAP 130 will automatically create or move the waypoint named 'MAP' at the navaid or map position.

## To activate a GOTO from the map display:

1. Press the GOTO key twice.

- 2. To select an existing user waypoint, highlight the waypoint on screen and press 🛲 .
- 3. To select a navaid, highlight the navaid on screen and press a 'MAP' waypoint, with the navaid symbol and text as the default icon and waypoint comment. Press are the waypoint and begin navigation.
- 4. To select a cursor position as your destination, move the arrow cursor to the desired position and press and isplay the position as the 'MAP' waypoint. Press are the waypoint and begin navigation.



- **A.** Press GOTO once to select a destination from a list of waypoints.
- **B.** Press GOTO twice to select a destination waypoint with the map cursor. If you are not selecting an existing waypoint as your destination, a new waypoint named 'MAP' will be created. Keep in mind that the MAP waypoint will be overwritten for each MAP GOTO. This allows you to navigate to onscreen navaids without permanently storing the navaid as a waypoint. If you want to save the MAP waypoint, rename it following the steps on page 39.



- **A.** The GOTO options page lets you start a TracBack route, select a destination from the nearest list, select a route to activate, or cancel the current GOTO destination.
- **B.** The nearest waypoints list limits the list to provide quick access to nearby anchorages, facilities, etc. which are stored as waypoints.

# **GOTO Key Options**

The GOTO options page provides a list of additional GOTO options that let you start a TracBack route, select a destination waypoint from the nearest waypoints list, select a route to navigate, or cancel the current GOTO destination.

# To display the GOTO options:

1. Press Menu .

### To select a menu option:

1. Highlight the desired option and press 💵.

The following options are available:

- **Start TracBack?** allows you to create and start navigation of a TracBack route back to the oldest track log point in memory (see pages 45-46 for more on using the TracBack function).
- Show All Wpts?— displays the GOTO waypoint list.
- Show Nearest Waypoints?— allows you to select the GOTO destination from a list of the nine nearest waypoints to your present position.

# To select a nearest waypoint as a GOTO destination:

- 1. Highlight the 'Show Nearest Waypoints' option and press 🛲 .
- 2. Select the desired waypoint and press EFFER.
- Select Route?— allows you to quickly select a stored route for navigation.

# To select a route to navigate:

1. Highlight the 'Select Route' option and press 🛲 .

- 2. Select the desired route and press ERT.
- **Cancel GOTO?** cancels the current GOTO destination and resumes navigation of any previously selected route.

## MOB

The GPSMAP 130's **man overboard function** (MOB) lets you simultaneously mark and set a course to a position for quick response to emergency situations.

#### To activate the MOB function:

1. Press the MOB key.

2. Press the ENE key to confirm and begin navigating to the MOB position.

Once a MOB has been activated, a MOB icon will appear on the map display, and the destination field on the map page will display the bearing, distance, and ETE to the MOB position based on your present speed and course.

#### To stop navigation to the MOB position:

1. Press the GOTO options page.

2. Select the 'Cancel GOTO' option and press EFF.

# **TracBack Navigation**

The third method of navigating to a destination is by using the GPSMAP 130's **TracBack** feature. The TracBack function allows you to retrace your path using the track log automatically stored in the receiver's memory, which will eliminate the need to store waypoints along the way. TracBack routes are created by reducing your track log into a route of up to 30 waypoints and activating an inverted route along those points. Once activated, a TracBack route will lead you back to the oldest track log point stored in memory, so it's good idea to clear the existing track log at the start of your current trip (e.g., your dock) before you get started.

# To clear the track log and define a starting point for a TracBack route:

1. Press the NENU key twice to display the main menu page.

2. Highlight the 'Track' option and press Even.

3. Select the 'Delete Track?' option and press Err.

4. Highlight the 'Yes' field and press ENTER .



- **A.** The GPSMAP 130's MOB mode can be used to set a course to a passing spot for quick response to emergency situations, fish strikes, etc.
- **B.** To define a starting point for a TracBack route, clear the track log.



- **A.** The TracBack feature uses your track log to create a route back to where you started.
- **B.** Once a TracBack is activated, the track log is divided into segments using temporary waypoints, and an inverted route is activated back to the oldest track log point in memory.

## To activate a TracBack route:

1. Press the Goto key, followed by the MENU key.

2. Highlight the 'Start TracBack?' option and press

Once a TracBack has been activated, the GPSMAP 130 will take the track log currently stored in memory and divide it into segments called 'legs'. Up to 30 temporary waypoints (e.g. T001) will be created to mark the most significant features of the track log in order to duplicate your exact path as closely as possible. To get the most out of the TracBack feature, remember the following tips:

• Always clear the track log at the point that you want to go back to (dock, etc.).

- The 'RECORD' option on the track log setup page must be set to 'Fill' or 'Wrap'.
- There must be at least two track log points stored in memory to create a TracBack route.
- If there are not enough available waypoints in memory to create a TracBack route, you will be alerted with a 'waypoint memory full' message, and the receiver will use available waypoints to create a route with an emphasis on the track log closest to the destination.
- If the track log interval is set to the 'Time' option, the route may not follow your exact path (keep the interval set to 'resolution' for best performance).
- If the receiver is turned off or satellite coverage is lost during your trip, the TracBack will draw a straight line between any point where coverage was lost and where it resumed.
- If the changes of direction and distance of your track log are very complex, 30 waypoints may not accurately mark your exact path. The receiver will then assign the 30 waypoints to the most significant points of your track, and simplify segments with fewer changes in direction.
- Whenever a TracBack route is activated, the receiver will automatically erase any temporary waypoints (e.g., 'T001') that are not contained in routes 1-20. If there are temporary waypoints stored in routes 1-20, the receiver will create any new temporary waypoints using the first three digit number available.

### Routes

The last way to navigate to a destination is to create a user-defined route. The GARMIN GPSMAP 130 system lets you create and store up to 20 reversible routes (numbered 1-20), with up to 30 waypoints each. Routes can be created and modified right from the map page, allowing you to see each route graphically on-screen as you create, review, modify or navigate the route. All of the GPSMAP 130's route functions are accessed through the main menu.

#### To create a route graphically:

- 1. Press the MENU key twice to display the main menu page.
- 2. Highlight the 'Routes' field and press error. The routes page will appear, showing all the routes currently stored in memory.
- 3. Press the MENU key to display the route options page.
- 4. Press EFFER to select the 'Create New Route' option.

The route edit page will appear, with the cursor displayed as an arrow pointer, and will allow you to select your route waypoints using one of two methods:

- 5. To add an existing waypoint or navaid to the route, use the arrow pointer to highlight the desired waypoint on screen and press [###].
- 6. To add a new waypoint to the route, use the arrow pointer to select the desired map position and press . Press . Press . Press .

As you add each new waypoint to the route, the data window at the top of the map display will show the route number you are creating, along with the first and last route waypoints of the route. A route line will appear on the map to indicate each completed leg, and a dotted line will appear to indicate the distance and bearing to the arrow pointer from the last route waypoint.

- 7. Repeat steps 5 and 6 until you have finished defining all route waypoints.
- 8. Press our to finish and enter review mode, or pros to return to the main page sequence.



- **A.** The route options page provides access to the GPSMAP 130's route functions.
- **B.** Use the arrow pointer and EDIT/ENTER to add waypoints to the route. The create waypoint page will appear whenever you have selected a position that is not already stored as a waypoint.



- **A.** To move a route waypoint, select the 'Move?' option and press EDIT/ENTER.
- **B.** Move the arrow cursor to the new waypoint position and press EDIT/ENTER to confirm.

Once a route has been created graphically (and the arrow has been pressed to finish), the map display will automatically enter the route review mode. The arrow pointer will be replaced by the map cursor, located at the last route waypoint. The route edit mode allows you to review and modify the route displayed through a pop-up window menu for each waypoint. You may also use the cursor to select an individual route leg and insert a new route waypoint.

#### To edit a route waypoint:

## 1. Use the cursor to highlight the desired route waypoint and press 🕅 .

A pop-up menu of editing choices will appear, with options for reviewing, removing, moving or inserting a route waypoint.

#### To review a route waypoint:

1. Highlight the 'Review?' option and press

#### To remove a route waypoint:

1. Highlight the 'Remove?' option and press [FFF].

#### To move a route waypoint:

- 1. Highlight the 'Move?' option and press
- 2. Move the cursor to the new map position and press EFF.

#### To insert new route waypoint(s) at the beginning or end of the route:

- 1. Select the first (to add waypoints to the beginning of the route) or last (to add waypoints to the end of the route) route waypoint with the map cursor, and press **GRE**.
- 2. Highlight the 'Insert?' option and press **EVER** .
- 3. Move the cursor to the new waypoint position and press ERE.
- 4. If you are not inserting an existing waypoint, press 🕮 to confirm the new waypoint.
- 5. Repeat steps 3 and 4 to insert additional waypoints, or press our to finish.

The GPSMAP 130's route edit mode also allows you to insert a new route way-point in any route leg using the map cursor.

# To insert a new waypoint between two existing route waypoints:

- 1. Use the cursor to select the leg you want to insert the new waypoint in (the route line will change to a dotted line when the leg is selected) and press [###].
- 2. Move the cursor to the new map position and press EFF.
- 3. If you are not inserting an existing waypoint, press 🛲 to confirm the new waypoint.

The route edit options page provides access to a variety of functions which can be used to review, activate, invert or edit the route as text and adjust the map view of the selected route.

# To display the route edit options:

1. Press Menu

# To select a menu option:

1. Highlight the desired option and press 💵.

The following options are available:

• Edit As Text?— allows you to modify a route by text entry.

# To edit a route by text entry:

- 1. Highlight the 'Edit As Text?' option and press IRR. The text edit page will appear, showing a list of all route waypoints, with the desired track and distance of each leg displayed.

# To review the selected waypoint:

1. Highlight the 'Review?' option and press 🛲 .



- **A.** A new route waypoint may be inserted into any route leg by pointing to the new waypoint or position and pressing EDIT/ENTER.
- **B.** The 'Edit As Text?' option allows you to review and modify waypoints by text data entry.



- **A.** To remove a route waypoint, highlight the waypoint on the map, press EDIT/ENTER, and select the remove option from the pop-up window.
- **B.** The route edit options page lets you activate, invert or deactivate the route you are editing. The 'Center On Vessel' and 'Center On First Wpt' options redraw the map to display the desired option.

#### To insert a new waypoint before the selected route waypoint:

- 1. Highlight the 'Insert?' option and press 🛲
- 2. Enter the name of the new waypoint using the rearest list, or press to select the new waypoint from the nearest list, waypoint list, or map display.
- 3. Press ERE to finish.

#### To remove the selected route waypoint:

1. Highlight the 'Remove?' option and press EFF.

### To change the selected route waypoint:

- 1. Highlight the 'Change?' option and press 💵.
- 2. Enter the name of the new waypoint using the rearest list, or press to select the new waypoint from the nearest list, waypoint list, or map display.

3. Press Entry to finish.

The **route edit options page** features five more functions. These functions may be selected by highlighting the desired function and pressing **EVE**:

- Activate Route?— activates the route you are editing and begins navigation.
- **Invert Route?** activates the route you are editing in reverse order and begins navigation.
- **Center On Vessel?** redraws route edit map with your vessel in the center of the display.
- **Center On First Wpt?** redraws route edit map with the first route waypoint in the center of the display.
- Deactivate Route?— stops navigation of the route currently selected.

To exit the route edit mode and return to the route list page, press the aur key.

## **Route List Page**

The GPSMAP 130's **route list page** displays all the routes currently stored in memory in numerical order, with the route number and comment displayed. Route 00 is always reserved for the TracBack route, while routes 1-20 serve as storage routes (route 20 is stored as the GPSMAP tour route, which may be deleted at any time). From the list, you may enter your own 16-character route comment and select a specific route for activation, editing or other management functions.

#### To enter a custom route comment:

1. Highlight the desired route and press 💵.

2. Press the left arrow key of the 🜑 keypad to clear the comment field.

3. Use the 🌑 keypad to enter the new route comment and press 🛲 .

Once you have selected a route from the route page, additional functions for that route are available from the route options page.

### To display the route options:

1. Press Menu .

#### To select a menu option:

1. Highlight the desired option and press 💵.

The following options are available from the route list page:

- Create New Route?— allows you to create a new route (see page 47).
- Activate Route?— activates the selected route and begins navigation.
- Invert Route?- activates the selected route in reverse order and begins navigation.
- Edit On Map?— allows you to edit the selected route graphically (see pages 48-49 for specific instructions).
- Edit As Text?— allows you to edit the selected route by text (see pages 49-50 for specific instructions).



- A. The route list page displays each route stored in memory, along with a 16-character user comment. The default comment is the name of the first and last route waypoint.
- **B.** The route list options page provides quick access to many route functions, including activating and deactivating a selected route.



- **A.** To delete all waypoints from a selected route, highlight the 'Clear Route?' option and press EDIT/ENTER.
- **B.** Once a route is cleared, all waypoints are removed from the route. They are still stored in memory, however.

# Route List Page Options (cont.)

• Clear Route?- allows you to clear all waypoints from the selected route.

### To clear the selected route:

- 1. Highlight the 'Clear Route?' option and press 🛲 .
- 2. Press ERE to confirm the clear route warning.

	Active Route
02	DIVE - FISH
We	VPOINT DIS ETE
D	COPY ROUTE
▶ F	Copy Route 02
-	To Route OG -
-	-
-	A X C
-	Are tou sure :
_	YES NO -
-1	
_	
_	M :
_	^h :
SI	1

• **Copy Route?—** allows you to copy the waypoints of a selected route to another route. The route copy function can be used to copy a TracBack route (route 00) to another route in order to either prevent losing the route the next time a TracBack route is activated, or save a modified version of an existing route without losing the original.

## To copy a route:

- 1. Highlight the 'Copy Route?' option and press **ERE**. The selected route will appear as the 'copy from' route, and the first open storage route will appear as the 'copy to' route.
- 2. Press Et to confirm. (If you'd like to change the route number that is being copied or the open route which is being copied to, highlight the appropriate field and press Ett; select the new route number and press Ett.
- Deactivate Route?— stops navigation of the route you are currently navigating.

#### **Active Route Page**

Act	Active Route			
02 DIVE	- FISH	1		
WAYPOINT	DIS	ETE		
DIVE	h	:		
REEF	9.00%	:		
WRECK	12.0%	:		
FISH	33.0%	:		
	h	:		
	h	:		
	<sup>b</sup>	:		
	h	:		
	<sup>b</sup>	:		
	h	:		
	h	:		
	h	:		
SIM				

Whenever you have activated a route in the GPSMAP 130 system, the **active route page** will appear in the main page sequence. The active route page shows each waypoint of the active route, with the waypoint name, desired track, cumulative distance and ETE or ETA for each waypoint from your present position. The current destination waypoint, the 'active to' waypoint, is marked with an arrow icon. As you navigate a route, the waypoint list will automatically update to indicate the next 'active to' waypoint first.

From the active route page, you can:

- Change the route comment- see page 51 for instructions.
- Edit the route on map- see pages 48-49 for instructions.

Additional functions for the active route are available from the **active route options page**.

To display the active route options:

1. Press Menu .

#### To select a menu option:

1. Highlight the desired option and press 💵.



Each waypoint on the active route page may be reviewed, deleted or changed right from the active route page. To edit an active route waypoint, highlight the desired waypoint and press EDIT/ENTER.

Select the desired function from the pop-up menu and press EDIT/ENTER.



The 'Change Data Fields?' option lets you specify what information is displayed for each route waypoint. Four data options are available: distance, desired track, and ETA or ETE to each route waypoint.

#### **Active Route Page Options**



The following options are available from the active route page:

- Invert Route?— activates the active route in reverse order and begins navigation.
- Activate Route?— reactivates the active route and selects the route leg closest to your current position as the new active leg.
- Edit On Map?— allows you to edit the selected route graphically (see pages 48-49 for specific instructions).
- Clear Route?- allows you to clear all waypoints from the selected route.
- **Copy Route?** allows you to copy the waypoints of the active route to another route.
- **Change Data Fields?** allows you to define the data displayed in the distance and ETE fields. four data options are available:
  - DIS- distance to active wpt DTK- desired track
  - ETE- estimated time enroute ETA- estimated time of arrival
- Restore Defaults?— resets all active route page options to the factory settings.
- Deactivate Route?- stops navigation of the route you are currently navigating.
- **Setup Simulator?** allows you to define speed, course and position values while in simulator mode. See the Getting Started Tour for more on using the simulator mode.

# Track Log Submenu

The GPSMAP's **main menu page's track submenu** lets you specify whether or not to record a track plot (an electronic recording of your path) and define how it is recorded. It also provides an indicator of the track memory used and selects functions to clear the track memory and start a TracBack route. The following functions are available:

- Record Mode— lets you select one of three track recording options:
  - Off– No track log will be recorded. Note that selecting the 'Off' setting will prevent you from using the TracBack feature.
  - Fill- a track log will be recorded until the track memory is full.
  - Wrap– A track log will be continuously recorded, wrapping through the available memory (replacing the oldest track data with new data).
- **Interval** defines the frequency with which the track plot is recorded. Three interval settings are available:
  - Time- records track plot based on a user-defined time interval.
  - Resolution- records track plot based upon a user-defined variance from your course over ground. The resolution option is the default setting and is recommended for the most efficient use of memory and TracBack performance. The distance value (entered in the interval field) is the maximum error allowed from the true course before recording a track point.
  - Distance- records track based on a user-defined distance between points.
- Interval Value— defines the distance or time used to record the track log.
- Delete Track?— allows you to clear the track log currently stored in memory.
- **Start TracBack?** converts the current track log into an inverted route and begins route navigation along the track log.

#### To reset all track options to the default settings:

1. Press MENU, followed by ERT.



- **A.** The 'Wrap' option will continuously record a track log, and replace the oldest track log point with new data. The 'Fill' option will record a track log until the memory is full.
- **B.** The track submenu's default settings may be quickly restored from the track options page.



TRIP & I	FUEL PLANNING	1	TRIP &	FUEL PLANNING
PLAN			PLAN	
Point-To-Po	pint		Point-To-P	oint
DIVE	to FIS		DIVE	to FISH
SPEED	17.0		SPEED	17.
FUEL FLOW	5.0/hr		FUEL FLOW	5.
DEPART	15-APR-96		DEPART	25-APR-9
	21:42			21:4
DTK 094	ໍ FUEL <b>9.7</b>		DTK 094	K FUEL <b>9.</b>
DIS 33.0	)% ETE 01:56		DIS 33.0	Dm ETE 01:
ETA 23:3	8ž RISE 11:41ž		ETA 23:3	82 RISE 11:2
DATE 15-A	PR SET 00:542		DATE 25-A	PR SET 01:0
SIM		B	SIM	

FISH 17.**0**%

APB-96

21:42% 9.7

01:56

11:27 01:033

5.0/h

A

#### **A.** To perform point-to-point planning, enter a 'TO' and 'FROM' waypoint, or leave the field blank if you want to use your present position.

**B.** Enter a date and time for your departure. The sunrise/sunset and ETA at the 'TO' waypoint will be displayed at the bottom of the page.

# **Trip and Fuel Planning**

The GPSMAP 130's **trip and fuel planning submenu** lets you plan and review distance, fuel, and ETE/ETA information between any two waypoints; your present position and a stored waypoint; or any part of a stored route. Sunrise and sunset information is also provided. Two planning modes are available: point-topoint and route planning.

#### To use the point-to-point planning mode:

- 1. Highlight the 'Trip & Fuel Planning' option from the main menu page and press EPER.
- 2. If the plan field is not set to 'Point-To-Point', press the menu key and select it from the options page.
- 3. Highlight the first waypoint field and press [1996]. Press the left arrow key to clear the field, and use the repeat to enter the name of the starting waypoint. You may leave the waypoint field blank to use your present position, or press the **Menu** key to select the waypoint from the nearest list, the waypoint list, or the map display. Press and to confirm the waypoint.
- 4. Move the field highlight to the second waypoint field and follow the steps above to select the destination waypoint.
- 5. Enter a speed for your trip in the speed field, or press men to select your current SOG for the speed value.
- 6. Enter an hourly fuel flow (if desired) in the fuel field, and press
- 7. Enter the date and time of your departure (the default date and time will be the current date and time in UTC or local time, whichever you have selected) and press ENT.

The bottom of the page will now display the desired track and distance between the two points; the estimated time enroute and fuel required; the date and time of your arrival; and the sunrise and sunset times at the destination for the date of arrival

The **route planning mode** lets you calculate the same planning information for any route stored in memory, in leg or cumulative leg or route totals.

### To use the route planning mode:

- 1. Highlight the 'Trip & Fuel Planning' option from the main menu and press 📖
- 2. If the plan field is not set to 'Route', press and select it from the options page.
- 3. Highlight the route number field and press **EVER**.
- 4. Use the 🗼 keypad to select the route you want to plan and press 📖
- 5. Highlight the leg field and press [FFF].
- 6. To plan the cumulative totals for the all route legs, select the 'ALL' option—or use the keypad to select a specific route leg to plan. Press error to confirm.
- 7. Enter a speed for your trip, or press **MEND** to select your current SOG for the speed value.
- 8. Enter an hourly fuel flow (if desired) in the fuel field, and press [FFF].
- 9. Enter the date and time of your departure (the default date and time will be the current date and time in UTC or local time, whichever you have selected) and press [###].

The bottom of the page will now display the planning information for the route leg selected or the cumulative values for the entire route. The route planning mode will also let you plan cumulative totals for multiple route legs by using the 'Hold First Waypoint?' selection from the options window.

# To plan multiple route legs:

- 1. Follow steps 1 through 6 above to select the last route leg you want to plan. For example, select leg 03 if you want to plan cumulative totals for the first three legs of the route (without including the rest of the route).
- 2. Enter the speed, fuel and date/time values as described in steps 7-9 above.
- 3. Press the MENU key to display the options page.
- 4. Select the 'Hold First Waypoint?' option and press **E**. The cumulative totals from the first route waypoint to the end of the selective leg will appear at the bottom of the page.



- **A.** To plan cumulative totals for an entire route, select the 'All' option from the leg field.
- **B.** To plan cumulative totals through a particular leg, select the 'Hold First Waypoint?' option from the Trip and Fuel Planning options page. Then enter the last leg you want to plan in the leg field.



- **A.** The system setup submenu provides access to the GPSMAP 130's time formats and contrast/back-light controls.
- **B.** When entering a time offset, be sure to select a positive or negative indicator to the left of the offset value.

The fuel and trip planning submenu also allows you to calculate the sunrise and sunset times for your present position or any waypoint for a selected date.

#### To use the sunrise/sunset planner:

- 1. Highlight 'Trip & Fuel Planning' option from the main menu and press 🛲
- 2. Highlight the first waypoint field and press and the left arrow key to clear the field, and use the keypad to enter the name of the desired waypoint. You may leave the waypoint field blank to use your present position, or press the keypad key to select the waypoint from the nearest list, the waypoint list, or the map display. To calculate the sunrise/sunset for your present position, leave both waypoint fields blank.
- 3. Press ENTER to confirm.
- 4. Highlight the date field and press 💵
- 5. Enter the date you want sunrise/sunset information for (the current date and year will be used as the default setting) and press errors. The sunrise and sunset times for the arrival date will be displayed at the bottom right of the planning page.

# Setup Submenus

The last four options available from the main menu page provide access to the various system, navigation, alarm and interface settings of the GPSMAP 130. The **system setup submenu** is used to select the operating mode, date and time formats, tone preferences, backlight timeout and display contrast.

- **Operational Mode** lets you select between normal operation and simulator mode. The GPSMAP 130's system only pretends to track satellites in simulator mode, and should not be used for actual navigation. Waypoints and routes created in simulator mode are saved in memory and are available for use in normal mode.
- **Time Offset** provides a data entry field to enter the time difference between UTC time and the local time. (See Appendix F for a list of time offsets.) When entering a time offset, be sure to select a positive or negative offset. Note that entering an offset will not automatically display local time. The *local* setting from the Date/Time Selection submenu must be selected.

- **Local/UTC** lets you choose to display the date and time in UTC (Greenwich Mean Time) time or local time offset from UTC time. The default setting is local with a '0' offset. (If you are boating in the United States, be sure to enter a negative time indicator in front of the appropriate time offset for your location).
- **Tone Selection** lets you select an audible tone to sound for either messages and keystroke confirmation (the default setting), messages only, or not to sound at all (the tone selection does not affect the external alarm operation).
- **Display Contrast** provides a slide bar to adjust the LCD screen contrast in order to compensate for changes in temperature or lighting conditions.
- **Backlight Timeout** provides an automatic shutoff for the GPSMAP 130's screen backlighting. Six settings are available: No Timeout (the backlight will stay on until it is turned off), 15 seconds (default setting); 30 seconds; and 1, 2, or 4 minutes. Keeping the timeout at the lowest acceptable setting will prolong the life of the backlight.

OPTIONS
Restore Defaults?
Setup Simulator?
Press MENU to see the Main Menu page.

The system setup page also features an options page that allows you to quickly reset all the system setup options to the factory default settings and define speed, course and position values while in simulator mode (see Getting Started Tour).

### To view the system setup page options:

1. Press the MENU key.

# To restore the default settings:

1. Highlight the 'Restore Defaults?' option, and press ERR.



- **A.** The tone preference will not affect external alarm operation.
- **B.** Keeping the backlight timeout at the lowest acceptable setting will prolong the useful life of the backlight.



- A. The GPSMAP 130 will also display position coordinates in eight grid formats.
- **B.** To enter a user magnetic variation, select the 'User Mag Var' option and enter a direction and value in the variation field.

# **Navigation Setup**

The navigation setup submenu is used to select a variety of navigation information including: position format, units of measure, and heading preferences. This submenu is also used to select map datums, set the CDI scale and adjust the builtin velocity filter. The following options are available:

- **Position Format** lets you select the coordinate system used to display position. The following formats are available:
  - hddd.ddddo (degrees)

• Irish grid

• Swedish grid

• Taiwan grid

- hddd<sup>o</sup>mm'ss.s" (deg/min/sec)
- German grid
- Maidenhead
- Swiss grid
- UTM/UPS grid
- Navigation Units selects the format for speed and distance measurements. You may select from nautical, statute or metric formats. (The default setting is nautical.)
- Depth Units selects the format for depth contour display on G-chart offshore chart cartridges. Depth contours can be displayed in feet, meters or fathoms. (The default setting is feet.)
- Heading lets you select what reference is used in calculating heading information. You can select to reference automatic magnetic variation, true north, grid heading or user magnetic variation. (The default setting is automatic.)

### To enter a user magnetic variation:

- 1. Highlight the 'Heading' field and press IRE. Select the 'User Mag Var' option and press
- 2. Press ISSE to access the variation field, and use the 🔘 keypad to enter the desired variation. Press **EVER** to confirm.
- CDI Scale provides a list of six CDI scale settings for the map page CDI: +/-0.10, 0.50, 1.0 (default). 5.0, 10.0 and 25.0 miles or kilometers. The scale represents the distance from the center of the scale to either end of the scale

• hddd<sup>o</sup>mm.mmm' (degrees and minutes) • British grid

- **CDI Steer To** allows you select a steer-to-center or steer-to-D-Bar orientation for graphic steering guidance. The steer-to-center selection displays your position as the vertical line on the scale, and your desired track as the center of the scale. The steer to D-Bar option displays your position as the center of the scale, with the desired track as the vertical line. The default setting is steer to center.
- **Map Datum** provides a list of the available map datums for use with the GPSMAP system. For a list of the available GPSMAP datums, see Appendix D. The default setting is WGS 84.
- **Velocity Filter** allows you to select the GPSMAP's response time to changes in track or ground speed. Three settings are available: automatic, on, or off. The 'auto' (default) setting will monitor the changes in your current track and speed and adjust the receiver's response time automatically. The 'on' setting allows you to manually enter a response time up to 240 seconds. Selecting a higher setting may be desirable in slow-speed applications with frequent changes in track.

VELOCITY	FILTER	
On		24 secs

### To enter a user defined velocity filter value:

- 1. Highlight the 'Velocity' field and press **EVER** . Select the 'On' option and press **EVER** .
- 2. Highlight the time value field.

3. Press Enter

4. Enter a value in seconds (up to 240) and press 🛲 to confirm.



- **A.** CAUTION! Using the incorrect map datum can seriously effect the accuracy of your GPS receiver. The GPS datum should always match the datum of the local chart you are using. If no datum information is indicated on the charts you are using, contact the chart manufacturer.
- **B.** Keeping the velocity filter on the 'Auto' setting will allow the GPSMAP 130 to automatically monitor and adjust the response time for track and speed calculations.



- **A.** The timer field can be set to count down from a specified interval or provide a running count of elapsed time.
- **B.** The 'On' setting of the arrival alarm will cause the alarm to sound only for the final destination waypoint of a route at the distance specified.

# Timers & Alarms Setup

The timer & alarms submenu is used to control various alarm/timer settings.

• **Timer** sounds an alarm when an entered interval (up to 99:59:59) has expired, or provides a continuous running clock timer to 99:59:59.

### To use the countdown timer:

- 1. Select the Count Down menu option.
- 2. Enter the desired time interval in the interval field, and press 🛲 .
- 3. Once the count down time has expired, an alarm message will appear, and the timer will automatically switch to the count up mode.
- 4. To reset the timer, select the reset option and press EPPER.
- **Clock Alarm** provides an alarm for the system clock. To use the clock alarm, select the 'On' option and enter the desired time of day in the time field.
- **Arrival Alarm** lets you specify an alarm to sound when you're a specified distance away from a destination waypoint. Three options are available:
  - Off- No arrival alarm will sound.
  - Auto- An arrival alarm will sound one minute before the destination, based upon your current speed and course over ground.
  - On- An arrival alarm will sound at the alarm distance specified in the distance field for the destination waypoint (the 'On' setting will only provide an arrival alarm for the final destination waypoint of the active route).
- **Crosstrack Alarm** provides an alarm for crosstrack error (XTK) when your vessel is off course by more than a specified distance, up to 99.99 (units).
- **Anchor Drag Alarm** lets you specify an alarm to sound when you've exceeded a specified drift distance, up to 9999 (units). Whenever the anchor alarm is triggered, an anchor icon will appear in the status bar.
## Input/Output Submenu

The Input/Output submenu lets you control interface settings for connecting external NMEA devices, a DGPS receiver or a personal computer. The 'Input/Ouput Format' field, at the top of the page, lets you specify one of seven interface formats:

**Data Transfer** is a proprietary interface that allows you to exchange data such as waypoints, routes and track logs between GPSMAP units or a GARMIN PC kit.

**No In/NMEA Out** provides navigation information to a compatible NMEA device such as an autopilot or radar. NMEA 0180, 0182, 0183 v.1.5 and 0183 v.2.0 output options are available. See Appendix A for additional NMEA sentence information.

No In/No Out provides no interfacing capabilities.

**RTCM In/NMEA Out** allows DGPS beacon receiver input and also provides selectable NMEA output.

RTCM In/No Out allows DGPS beacon receiver input, with no output capabilities.

**NMEA In/No Out** allows input from a NMEA compatible external device, such as a Yeoman<sup>®</sup> Plotter, with no output capabilities.

**NMEA In/NMEA Out** provides the same input capabilities as NMEA IN, with selectable NMEA output.

When the 'Data Transfer' option is selected, you'll need to specify what information to request or send to the remote unit through the Transfer Mode field. The 'slave' setting lets you control all data transfer from the 'external' GPS receiver, or PC while the other settings request or send specific data from the primary unit.



- A. The data transfer options allow you to send or receive almanac data, proximity waypoints, routes, track log data and waypoints to another GARMIN GPS or PC Kit.
- **B.** The NMEA In setting allows you to accept NMEA data from a Yeoman plotter or other compatible device.



- **A.** Select the desired format from the NMEA field. The baud rate will automatically be set to the appropriate speed.
- **B.** After entering a DGPS frequency, set the bit rate to the speed indicated on the USCG station chart. DGPS coverage, frequencies and bit rates are available from the Coast Guard's automated FAX service (703-313-6932).

# Using NMEA & DGPS Interface Settings

If you are using an NMEA interface format, the NMEA format must be specified in the NMEA format field that will automatically appear when an NMEA option is selected. The appropriate baud rate will be set automatically.

## To select an NMEA format:

- 1. Select a NMEA IN/OUT format from the options page.
- 2. Highlight the NMEA Format field and press
- 3. Select a NMEA sentence format and press
- 4. The baud rate will automatically be set to the appropriate speed. If you have selected an NMEA IN/OUT setting, you must use the same NMEA format for both the input and output device.

# **Tuning DGPS Stations**

If the I/O Format is set to accept RTCM input/NMEA Output for connecting a differential-ready GPS beacon receiver, you will need to tune a frequency in the tuning field and select a bit rate. The default frequency will be 304.0 kHz, with a bit rate of 100 bps, or the last DGPS frequency/bit rate selected.

## To tune a DGPS frequency:

- 1. Select the 'RTCM In/NMEA Out' format from the options page.
- 2. Highlight the beacon receiver frequency field and press 🛲 .
- 3. Enter the desired frequency and press errors. If you are using an automatically-tuned DGPS receiver, you may enter 000.0 for the frequency.
- 4. Press I to select a bit rate. Five bit rates are available: 0 (used for automatically-tuned DGPS receivers), 25, 50, 100 and 200 bps. Press
  to confirm. The DGPS status, along with the signal-to-noise ratio of the tuned station, will be displayed at the bottom of the page.

## Installing & Removing G-chart Cartridges

The GARMIN GPSMAP 130 system uses G-chart offshore or inland cartography to display digital charts on-screen. G-chart cartridges are installed in the card slot located at the bottom right of the GPSMAP unit. G-chart cartridges may be installed or removed at any time, whether the unit is on or off.

### To install a G-chart cartridge:

- 1. Open the cartridge door.
- 2. Insert the card (label facing front and G-chart logo at top) into the slot.
- 3. Use your thumb to firmly push the cartridge into place (until the cartridge will not go any further into the unit). If your GPSMAP 130 is on, a confirmation tone will sound when the cartridge has been properly installed and accepted.
- 4. Close the cover.

If you insert a G-chart cartridge and get a 'card format not recognized' message, try removing the card and reinserting it. If the card is still not recognized, contact the dealer you purchased it from for assistance. G-chart cartridges are not waterproof, should not be exposed to moisture or excessive static charges, and should be stored in the anti-static bag supplied with the cartridge.

#### To remove a G-chart cartridge:

- 1. Open the cartridge door.
- 2. Grasp the card at the bottom groove and pull firmly.
- 3. If your GPSMAP is on, a confirmation tone will sound when the G-chart cartridge has been removed.





- **A.** Map outlines for *G*-chart offshore cartography.
- **B.** Map outlines for *G*-chart inland cartography.

## Using G-chart Cartography

Once a G-chart cartridge has been inserted, the map coverage outlines for the cartridge will automatically appear on-screen. Keep in mind that the display will not automatically scroll to the map area or zoom to a level where you can see the coverage outlines. If you do not immediately see the outlines, scroll the cursor to the broad geographic area covered by the chart and zoom out to another map scale.

The large outlined box shown is the main chart, which serves as the boundary area for the entire cartridge. The small outlined box inside the main box are subcharts, which provide more detailed coverage of the area indicated. To view the detailed cartography of any subchart, scroll the cursor to the subchart outline and use the  $\clubsuit$  key to zoom in to smaller range scales. If the map outlines still do not appear, check the 'Map Outlines' setting on the map options page to make sure they are set to appear (see page 26).

Whenever you zoom past the usable range of the current electronic chart, the range field will display 'Ovr Zm' or 'No Map'. These warnings indicate that although you may still have cartography, you should exercise extreme caution using the data. See page 25 for more information on Overzoom and No Map modes.

When a G-chart cartridge is installed, the GPSMAP 130's system will automatically use the best available chart for display. As you enter and exit various subcharts, the system will automatically display the appropriate chart for the area you are in. When you leave the area covered by the main map of a cartridge, the GPSMAP 130 will default back to using the built-in 64 nm database if it is available at the current scale.

If you are not seeing certain map items (navaids, depth contours, etc. on offshore cartridges; highways, boat ramps, etc. on inland cartridges), check the map configuration settings available from the map options page.

## Installing the GPSMAP 130

The GPSMAP 130 must be properly installed according to the following instructions to get the best possible performance. The GPS antenna should be installed first, followed by the display unit. To complete the installation, you'll need the appropriate fasteners for your installation, and a 1" x 14-thread marine antenna mount available at most marine dealers.

### Mounting the GPS antenna

The antenna should be mounted in a location that has a clear, unobstructed view of the sky in all directions to ensure the best reception. Avoid mounting the antenna where it will be shaded by the boat's superstructure, a radome antenna, or mast. Sailboat users should avoid mounting the antenna high on the mast to prevent inaccurate speed readings caused by excessive heeling. Most marine VHF and loran antennas will not seriously degrade the GPS antenna's reception. Never paint the antenna or clean it with harsh solvents.

The GARMIN antenna screws directly onto any standard 1" x 14-thread antenna mount. If you need to raise the antenna to avoid shading, try using a 1" x 14-thread extension mast available at most marine dealers.

#### To install the GPS antenna:

- 1. Screw the antenna directly onto the 1" x 14-thread mount.
- Route the cable to the mounting location of the display unit. Use the appropriate tiewraps, escutcheon plates and sealant to secure the cable along the route and through any bulkhead or deck.
- 3. Once the GPSMAP unit has been installed, connect the cable to the antenna connector on the back of the display unit. Make sure that you turn the antenna cable connector 1/4 turn clockwise to lock the cable into place.





# Mounting the GPSMAP 130 Unit

The GPSMAP 130's compact, waterproof case is suitable for mounting in exposed locations or at the nav station. The unit comes with a gimbal bracket that can be used for surface or overhead mounting. When choosing a location for the display unit, make sure you consider the following conditions:

- There should be at least a 2" (5 cm) clearance behind the case to allow connection of the antenna and power/data cables.
- The unit should not be mounted where it is exposed to excessive temperatures for extended periods (see page 69).
- You should provide adequate clearance for the G-chart cartridge cover to swing open freely. You may have to swivel the unit to get a firm grip on the cartridge.
- The mounting surface should be heavy enough to support the unit and protect it from excessive vibration and shock.
- For flush mounting, make sure the flat panel is between 0.08" and 0.52" (2 to 13.2mm) thick to use the cam lobe built into the mounting bracket.

## To install the GPSMAP unit:

- 1. Place the mounting bracket in the desired location.
- 2. Mark and drill the four mounting holes for the fastener you are using. Note that the GPSMAP 130 may also be used with a Johnny Ray JR-400 swivel mount.
- 3. Fasten the bracket to the surface using the appropriate fastener.
- 4. Insert the GPSMAP 130 into the mounting bracket. The bracket is designed for a tight fit to provide additional support when swiveling the unit.
- 5. Screw the two mounting knobs through the bracket and into the display case.
- 6. Connect the power/data and antenna cables to the back of the unit, making sure the locking rings are fully tightened on both connectors.



#### To flush mount the GPSMAP 130:

- 1. Cut a 4.15" W x 4.67" H (105.4 x 118.6mm) hole in panel.
- 2. Place GPSMAP 130 into hole from the front until its flange rests against the mounting surface.
- 3. From the back side of the panel, loosely attach the bracket so that the slot in the ratchet area points away from the mounting panel.
- 4. Rotate the bracket downward until the panel is pinched tightly between the unit's flange and bracket lobe.
- 5. Tighten knobs and connect the power/data and antenna cables.



## WARNING!

The temperature range for the GPSMAP 130 is -4 to +158°F (-20 to 70°C). Extended exposure to temperatures exceeding this range (in storage or operating conditions) may cause failure of the LCD screen. This type of failure and related consequences are NOT covered by the manufacturer's limited warranty.



DGPS corrections are accepted in RTCM-104 v. 2.0 format through the NMEA In (BROWN) harness lead. The GARMIN GBR 21 is the recommended beacon receiver for use with the GPSMAP system.Other receivers with the correct RTCM format may be used, but may not correctly display status or allow tuning control from the GPSMAP unit.

## Connecting the Power/Data Cable

The power/data cable connects the GPSMAP 130 to a 10-40 volt DC system and provides interface capabilities for connecting external devices, including an external alarm. The color code in the diagram below indicates the appropriate harness connections.



The following formats are supported for connection to up to 3 NMEA devices:

- NMEA 0180/NMEA 0182
- NMEA 0183 version 1.5

Approved sentences— GPBWC, GPGLL, GPRMB, GPRMC, GPXTE, GPVTG, GPWPL, GPBOD Proprietary sentences— PGRMM, PGRMZ (alt.), PSLIB (beacon receiver control input)

• NMEA 0183 version 2.0

Approved sentences— GPGGA, GPGLL, GPGSA, GPGSV, GPRMB, GPRMC, GPRTE, GPWPL, GPBOD

Proprietary sentences— PGRME (estimated error), PGRMM (map datum)

PGRMZ (altitude), PSLIB (beacon rec. control input)

# **GPSMAP 130 Specifications**

## PHYSICAL

Case:	Waterproof, dry nitrogen-filled
Size:	4.9"H x 5.3"W x 2.4"D
	(12.5 x 13.5 x 2.4 cm)
Weight:	Less than 1 lb. (454g)
Temperature Range:	5° to 158°F (-15° to 70°C)

### PERFORMANCE (GPSMAP 130)

Receiver:	12-channel PhaseTrac12
Acquisition Time:	Approx. 15 seconds (warm) Approx. 45 seconds (cold) Approx. 5 minutes (AutoLocate™)
	Approx. 5 minutes (Search the sky)
Update Rate:	l/second, continuous
Position Accuracy:	1-5 meters (3-16 ft.)* 15 meters (49 ft.) RMS**
Velocity Accuracy:	0.1 knot RMS steady state, 90 knots max.
Dynamics:	Performs to specification to 6g <sup>3</sup>

## POWER

Input:	10-40v DC
Usage:	3 watts max.

Specifications subject to change without notice.

\* With optional GARMIN GBR 21 Beacon Receiver Input.

\*\* Subject to accuracy degradation to 100m 2DRMS under the U.S. DOD-imposed Selective Availability Program.





The GPSMAP 130 uses an on-screen message prompt to alert you to important information. Whenever a message appears, press the **PAGE** key to view the message.

Alarm Clock—The alarm clock has sounded.

Anchor Drag Alarm-You have drifted out of the specified distance range.

**Approaching**—You are less than one minute away from reaching a destination waypoint at your present speed over ground.

Arrival At—You have arrived at the destination waypoint.

**Can't Change An Active Waypoint**—You have attempted to change the 'active to' or 'active from' waypoint. Clear the active route or GOTO before making your changes.

**Card Format is Not Recognized**—The cartridge inserted is not readable by the GPSMAP system and may be damaged. Reinsert the cartridge to make sure it is properly installed. If the cartridge is still not recognized, call the G-chart information line at 1-800-427-6460.

Cross-Track Alarm-You have exceeded the off-course distance specified in the CDI setup.

**Data Transfer is Complete**—The receiver is finished uploading or downloading information to the connected device.

**Database Memory has Failed**—The built-in 64 nm database has failed. See an authorized service center for repair.

**Degraded Accuracy**—The accuracy of your GPSMAP system has been degraded beyond 500 meters due to poor satellite geometry or data quality. You should check other navigational sources to verify the position indicated.

Max Calibration Is 5000mt (16,400 ft)—You have exceeded the maximum possible map calibration.

**Memory Battery Power is Low**—The internal battery that stores waypoints, routes and track plots needs to be replaced. Take your unit to an authorized GARMIN service center for installation of a new battery.

**Need Altitude**—Your GPSMAP system needs the altitude to maintain a position fix due to poor satellite coverage. Enter your approximate altitude on the initialize position page.

**Need to Select Init Method**—The GPSMAP 130 needs to be initialized to your present position. See pages 1-2 for complete instructions on initialization.

**No Differential GPS Position**—Not enough data is being received to compute a DGPS position.

**Oscillator Needs Adjustment**—The GPSMAP 130 has detected excessive drift in its internal oscillator, which may result in longer acquisition times. Take the unit to an authorized GARMIN service center for adjustment.

**Poor GPS Coverage**—The GPSMAP 130 cannot acquire the necessary number of satellites to compute a position.

**Power Down and Re-init**—The GPSMAP 130 cannot calculate a position due to abnormal satellite conditions. Power down and verify the last position shown by other means.

**Proximity Alarm**—You have entered the alarm radius for the proximity waypoint indicated.

Proximity List Full—You have used all nine proximity waypoints.

**Proximity Overlaps Another Prox Wypt**—The alarm radius specified overlaps the area specified for another proximity waypoint. (See section 10 for more information on proximity overlaps.)

**RAM has Failed**—The random access memory has failed and the unit is not operable. Take your unit to an authorized GARMIN service center for repairs.

**ROM has Failed**—The unit's permanent memory has failed and the unit is not operable. Take your unit to an authorized GARMIN service center for repairs.

**Received Invalid Waypoint**—A waypoint was received during upload transfer that has an invalid identifier.

**Receiver has Failed**—A failure in receiver hardware has been detected. If this message persists, do not use the unit and take it to an authorized dealer for repair.

**Route Already Exists**—The route number you are trying to copy to is already used.

Route Does Not Exist—The route number you are trying to use or copy is not defined.

Route is Full—You have attempted to add more than 30 waypoints to a route.

Route Memory is Full—You have attempted to create more than 20 routes.

**Route Waypoint was Deleted**—A route waypoint entered does not exist in the database and has been deleted from the route.

**RTCM Input has Failed**—DGPS data being received has been lost. You are no longer receiving the beacon signal.

Searching the Sky-The GPSMAP 130 is searching the sky for almanac data.



**Stored Data was Lost**—All waypoints, routes and almanac data has been lost due to internal battery failure.

**There is No RTCM Input**—The beacon receiver is not properly connected or baud rates do not match.

Timer Has Expired—The countdown timer has expired.

**Track Memory is Full**—The track memory is full and no additional track plot will be recorded until the track memory has been cleared or set to wrap mode.

Wypt Already Exists—The waypoint name you've entered already exists in memory.

**Waypoint Memory is Full**—You have used all 250 waypoints in the GPSMAP 130 system.

SECTION APPENDIX Map Datums

The GPSMAP's built-in worldwide database includes chart coverage down to 64 nm (120 km) for the areas outlined above. Note that the GPSMAP database is only valid to 68°15' of latitude. The maximum cursor latitude is 85°05', and the maximum waypoint latitude is 89°24.543 north or south.



Adindan	Adindan- Ethiopia, Mali,	Astrln Geod '84	Australian Geod '84-
	Senegal, Sudan		Australia, Tasmania Island
Afgooye	Afgooye- Somalia	Austria	Austria
AIN EL ABD '70	AIN ELANBD 1970- Bahrain Island, Saudi	Bellevue (IGN)	Efate and Erromango Islands
	Arabia	Bermuda 1957	Bermuda 1957- Bermuda
Anna 1 Ast '65	Anna 1 Astro '65- Cocos I.		Islands
ARC 1950	ARC 1950- Botswana, Lesotho, Malawi,	Bogata Observ	Bogata Obsrvatry- Colombia
	Swaziland, Zaire, Zambia, Zimbabwe	Campo Inchspe	Campo Inchauspe- Argentina
ARC 1960	Kenya, Tanzania	Canton Ast '66	Canton Astro 1966-
Ascnsn Isld '58	Ascension Island '58-		Phoenix Islands
	Ascension Island	Cape	Cape- South Africa
Astro B4 Sorol	Sorol Atoll- Tern Island	Cape Canavrl	Cape Canaveral- Florida,
Astro Bcn "E"	Astro Beacon "E"- Iwo Jima	-	Bahama Islands
Astro Dos 71/4	Astro Dos 71/4- St. Helena	Carthage	Carthage- Tunisia
Astr Stn '52	Astronomic Stn '52-	СН-1903	CH 1903- Switzerland
	Marcus Island	Chatham 1971	Chatham 1971- Chatham
Astrln Geod '66	Australian Geod '66-		Island (New Zealand)
	Australia, Tasmania Island	Chua Astro	Chua Astro- Paraguay

Corrego Alegr	Corrego Alegre Brazil	Karayalan Islud	Karquelen Island		05051011
Diakarta	Diakarta (Batavia), Sumatra	Kertan 1948	West Malaysia Singapore		SECTION
Djakarta	Island (Indonesia)	L C 5 Astro	Cauman Brac Island	APPENDIX	
Dos 1968	Dos 1968- Gizo Island	Liboria 1064	Liberia 1064 Liberia		
203 1900	(New Georgia Islands)	Liberta 1907	Luzon Mindanao Island	Map Datums	
Easter Isld 67	Easter Island 1967	Luzon Philippino	Luzon Philippines		
European 1950	European 1950- Austria.	Luzon r imppine	(excluding Mindanao Isl.)		
	Belgium, Denmark,	Mahe 1971	Mahe 1971- Mahe Island		
	Finland, France, Germany,	Marco Astro	Marco Astro- Salvage Isl		
	Gibraltar, Greece, Italy,	Marco Histro	Massawa- Eritrea (Ethiopia)		
	Luxembourg, Netherlands,	Merchich	Merchich- Morocco		
	Norway, Portugal, Spain,	Midway Ast '61	Midway Astro '61- Midway		
	Sweden, Switzerland	Minna	Minna- Nigeria		
European 1979	European 1979- Austria,	NAD27 Alaska	North American 1927-		
	Finland, Netherlands,		Alaska		
	Switzerland	NAD27 Bahamas	North American 1927-		
Finland Havfrd	Finland Hayford Finland		Bahamas (excluding San		
Candajika Basa	Candajika Base Pepublic		Salvador Island)		
Galluajika Dase	of Maldives	NAD27 Canada	North American 1927-		
Geod Datm '49	Geodetic Datum '49-		Canada and Newfoundland		
ocou buill 15	New Zealand	NAD27 Canal Zone	North Am. 1927- Canal		
Guam 1963	Guam 1963- Guam Island		Zone		
Gux 1 Astro	Guadalcanal Island	NAD27 Caribbean	North American 1927-		
Hjorsey 1955	Hjorsev 1955- Iceland		Caribbean (Barbados,		
Hong Kong '63	Hong Kong		Caicos Islands, Cuba,		
Hu-Tzu-Shan	Taiwan		Dom. Rep., Grd. Cayman,		
Indian Bngldsh	Indian- Bangladesh, India,		Jamaica, Leeward and Turks Islands)		
0	Nepal	NAD27 Central	North American 1027-		
Indian Thailand	Indian- Thailand, Vietnam	MID27 Central	Central America (Belize		
Indonesia '74	Indonesia '74		Costa Rica, El Salvador,		
Ireland 1965	Ireland 1965- Ireland		Guatemala, Honduras,		
ISTS 073 Astro	ISTS 073 ASTRO '69-		Nicaragua)		
	Diego Garcia	NAD27 CONUS	North Am. 1927- Mean		
Johnston Island	Johnston Island Kandawala		Value (CONUS)		
	Kandawala- Sri Lanka	NAD27 Cuba	North American 1927-		
Kandawala	Sri-Lanka		Cuba		75

SECTION **APPENDIX Map Datums** 

NAD27 Greenland	North American 1927- Greenland (Hayes Peninsula)
NAD27 Mexico	N. American 1927- Mexico
NAD27 San Salvadr	North American 1927- San Salvador Island
NAD83	North American 1983- Alaska, Canada, Central America, CONUS, Mexico
Nahrwn Masirah llnd	Nahrwn- Masirah Island (Oman)
Nahrwn Saudi Arbia	Nahrwn- Saudi Arabia
Nahrwn United Arab	Nahrwn- United Arab Emirates
Naparima BWI	Naparima BWI- Trinidad and Tobago
Obsrvtorio '66	Observatorio 1966- Corvo and Flores Islands (Azores)
Old Egyptian	Old Egyptian- Egypt
Old Hawaiian	Old Hawaiian- Mean Value
Oman	Oman- Oman
Ord Srvy Grt Britn	Old Survey Grt Britn- England, Isle of Man, Scotland, Shetland Isl., Wales
Pico De Las Nieves	Canary Islands
Potsdam	Germany
Pitcairn Astro '67	Pitcairn Astro '67- Pitcairn
Prov So Amricn '56	Prov So Amricn '56- Bolivia, Chile,Colombia, Ecuador, Guyana, Peru, Venezuela
Prov So Chilean '63	So Chilean '63- S. Chile
Puerto Rico	Puerto Rico & Virgin Isl.
Qatar National	Qatar National- Qatar
Qornoq	Qornoq- South Greenland

Rome 1940 Santo (Dos) Sao Braz Sapper Hill '43 Schwarzeck South Asia Southeast Base Southwest Base Timbalai 1948 Tokyo Tristan Astro '68 Viti Levu 1916 Wake-Eniwetok WGS 72 WGS 84 Zanderij Qornoq- South Greenland

Reunion

RT 90

Reunion- Mascarene Island Rome 1940- Sardinia Isl. Sweden Santo (Dos)- Espirito Santo Sao Braz- Sao Miguel, Santa Maria Islands Sapper Hill 1943- East Falkland Island Schwarzeck- Namibia South American '69 S. American '69- Argentina, Bolivia, Brazil, Chile, Colombia, Ecuador, Guyana, Paraguay, Peru, Venezuela, Trin/Tobago South Asia- Singapore Southeast Base- Porto Santo and Madiera Islands Southwest Base- Faial. Graciosa, Pico, Sao Jorge and Terceira Islands Timbalai 1948- Brunei and E. Malaysia (Sarawak and Sabah) Tokyo- Japan, Korea, Okinawa Tristan Astro 1968- Tristan da Cunha Viti Levu 1916- Viti Levu/ Fiji Islands Wake-Eniwetok- Marshall World Geodetic System 72 World Geodetic System 84 Zanderij- Surinam

**Almanac Data**—The satellite constellation information (including location and health of satellites) that is transmitted to your receiver from every GPS satellite. Almanac data must be acquired before GPS navigation can begin.

Bearing (BRG)—The compass direction from your position to a destination.

Course Over Ground (COG)—Direction of movement relative to a ground position.

Crosstrack Error (XTK)—The distance you are off a desired course in either direction.

Desired Track (DTK)—The compass course between the 'from' and 'to' waypoints.

**Differential GPS (DGPS)**—An extension of the GPS system that uses land-based radio beacons to transmit position corrections to GPS receivers.

Estimated Time of Arrival (ETA)—The time of day of your arrival at a destination.

**Estimated Time Enroute (ETE)**—The time remaining to your destination at your present speed.

**Grid**—A coordinate system that projects the earth on a flat surface, using square zones for position measurements.

Ground Speed (SOG)—The velocity you are travelling relative to a ground position.

Latitude—A north/south measurement of position perpendicular to the earth's polar axis.

**Longitude**—An east/west measurement of position in relation to the Prime Meridian, an imaginary circle that passes through the north and south poles.

Position—An exact, unique location based on a geographic coordinate system.

**Turn (TRN)**— The difference and direction in degrees between the bearing to your destination and your course over ground. The TRN value is used to indicate what direction, and how many degrees, to turn to get back on course.





**Universal Time Coordinated (UTC)**— The time of day at the prime meridian (0° longitude) in Greenwich, England.

**Universal Transverse Mercator- (UTM)**— A grid coordinate system that projects global sections onto a flat surface to measure position in specific zones.

Velocity Made Good (VMG)—The speed you are travelling in the direction of the destination.

**Waypoint**—A specific location saved in the receiver's memory.



The chart below gives an approximate UTC time offset for the various longitudinal zones. Check with local charts for more detailed information. If you are in daylight savings time, add one hour to the offset.

Longitudinal Zone	Offset
W180.0° to W172.5°	-12
W172.5° to W157.5°	-11
W157.5° to W142.5°	-10
W142.5° to W127.5°	-9
W127.5° to W112.5°	-8
W112.5° to W097.5°	-7
W097.5° to W082.5°	-6
W082.5° to W067.5°	-5
W067.5° to W052.5°	-4
W052.5° to W037.5°	-3
W037.5° to W022.5°	-2
W022.5° to W007.5°	-1
W007.5° to E007.5°	0
E007.5° to E022.5°	1
E022.5° to E037.5°	2
E037.5° to E052.5°	3
E052.5° to E067.5°	4
E067.5° to E082.5°	5
E082.5° to E097.5°	6
E097.5° to E112.5°	7
E112.5° to E127.5°	8
E127.5° to E142.5°	9
E142.5° to E157.5°	10
E157.5° to E172.5°	11
E172.5° to E180.0°	12



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